

Time Series Analysis

Spring 2024

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Outline of the lecture

- Regression based methods, 1st part:
 - Ordinary Least Squares (OLS)
 - Predictions = forecast
 - Global Trend Model
 - Weighted Least Squares (WLS)

General form of the regression model

$$Y_t = f(\mathbf{X}_t, t; \boldsymbol{\theta}) + \varepsilon_t$$

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Y_t is the output we aim to model

\mathbf{X}_t indicates the p independent variables $\mathbf{X}_t = (X_{1t}, \dots, X_{pt})^T$

t is the time index

$\boldsymbol{\theta}$ indicates m unknown parameters $(\theta_1, \dots, \theta_m)^T$

ε_t is a sequence of random variables with mean zero, variance σ_t^2 , and $\text{Cov}[\varepsilon_{t_i}, \varepsilon_{t_j}] = \sigma_t^2 \Sigma_{ij}$

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For now we restrict the discussion to the case where \mathbf{X}_t is non-random and thus we write \mathbf{x}_t instead of \mathbf{X}_t .

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- Regression based methods, 1st part:
 - **Ordinary Least Squares (OLS)**
 -
 -
 -

Ordinary Least Squares (OLS)

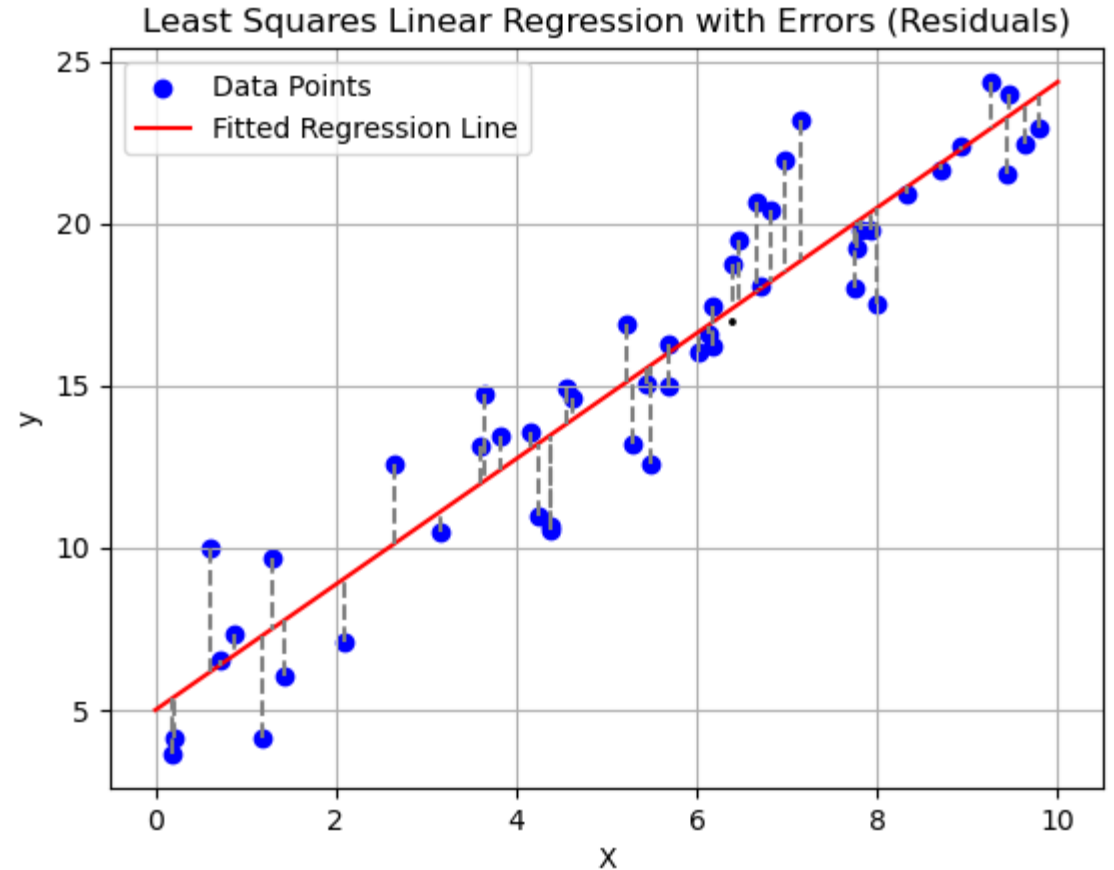
Observations (data):

$$(y_1, \mathbf{x}_1), (y_2, \mathbf{x}_2), \dots, (y_n, \mathbf{x}_n)$$

OLS estimates (of the parameters) are found by minimizing the sum of squared residuals:

$$S(\boldsymbol{\theta}) = \sum_{t=1}^n [y_t - f(\mathbf{x}_t; \boldsymbol{\theta})]^2 = \sum_{t=1}^n \varepsilon_t^2(\boldsymbol{\theta})$$

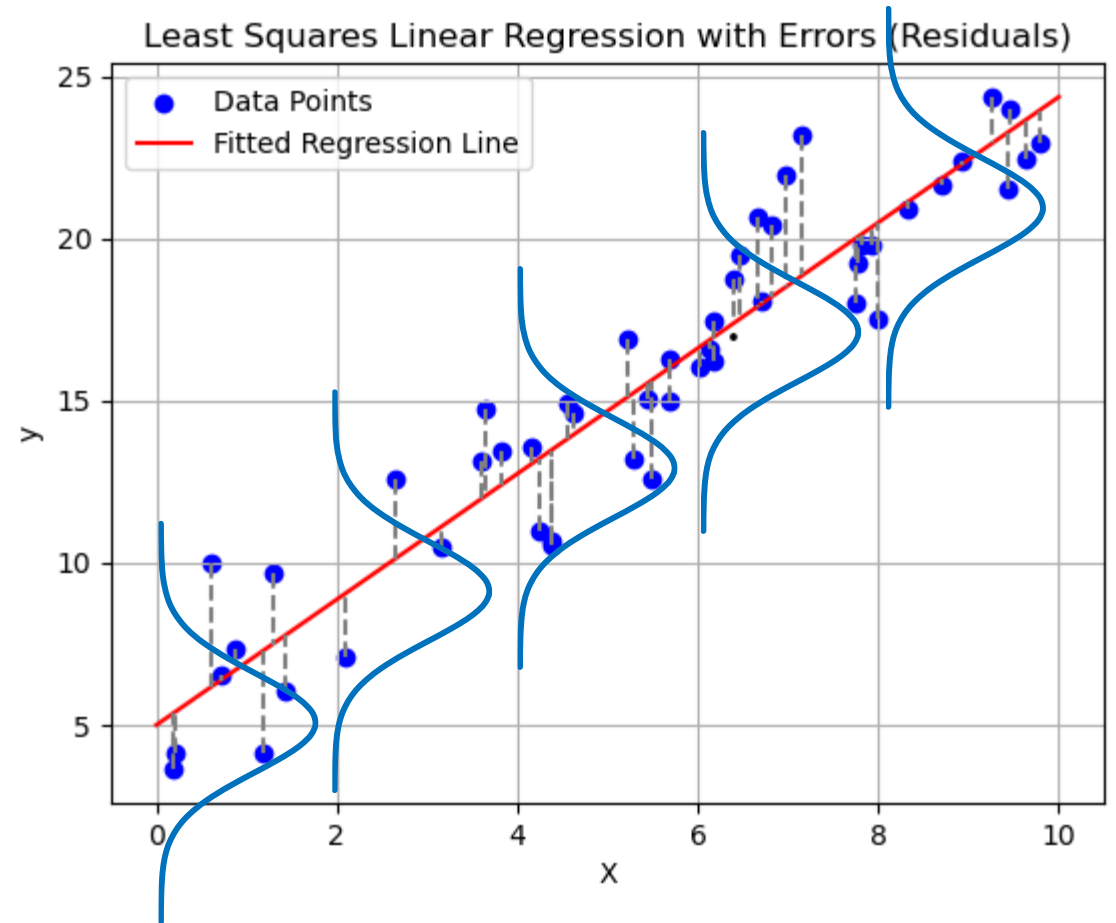
(sometimes also called "RSS")



OLS - model assumptions

Errors must be assumed to all have the same variance and be mutually uncorrelated

Errors are "i.i.d"



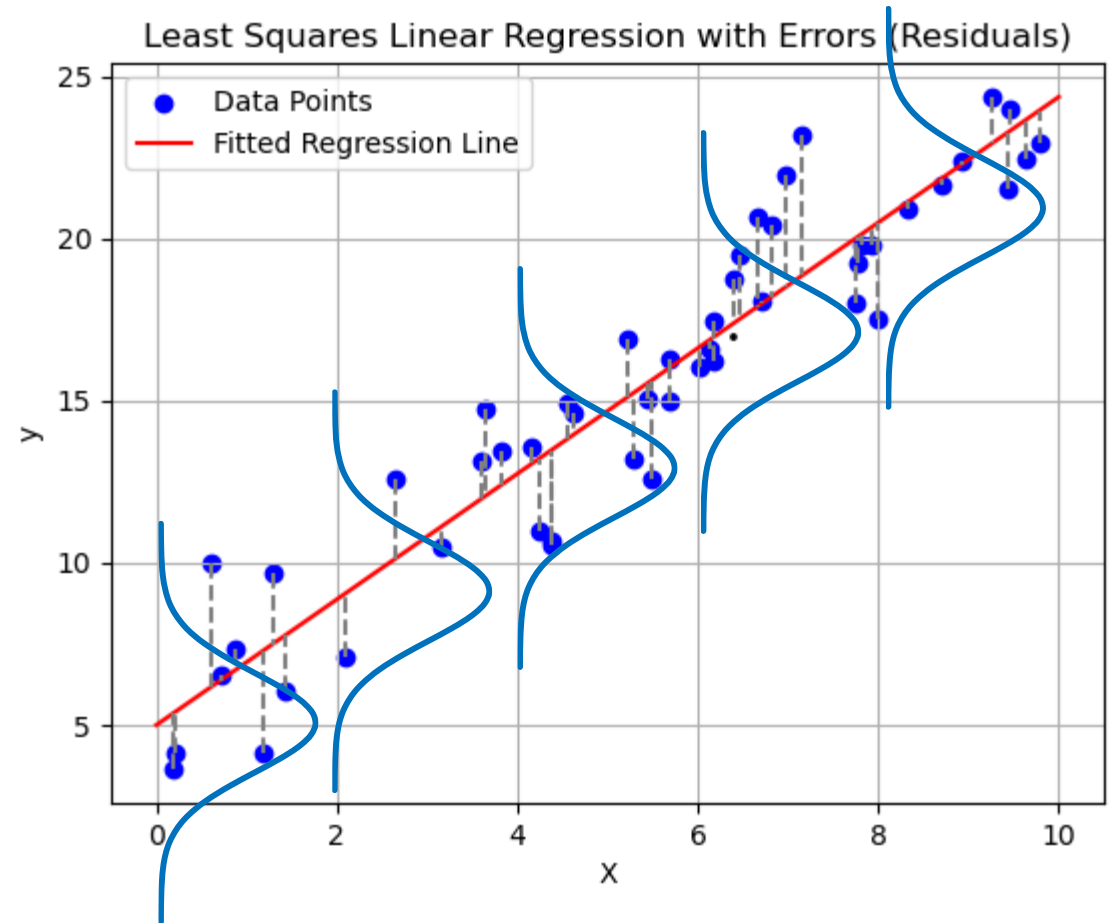
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$$\text{Cov}[\varepsilon_{t_i}, \varepsilon_{t_j}] = \sigma_t^2 \Sigma_{ij}$$

$$\Sigma = \begin{bmatrix} 1 & 0 & 0 & \dots & 0 \\ 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & 1 \end{bmatrix}$$



OLS – variance of model errors and of parameters

The variance of the model errors is estimated as:

$$\hat{\sigma}^2 = \frac{S(\hat{\boldsymbol{\theta}})}{n - p}$$

where p is the number of estimated parameters.

The variance-covariance matrix of the estimates is approximately

$$V[\hat{\boldsymbol{\theta}}] = 2\hat{\sigma}^2 \left[\frac{\partial^2}{\partial^2 \boldsymbol{\theta}} S(\boldsymbol{\theta}) \right]^{-1} \Bigg|_{\boldsymbol{\theta}=\hat{\boldsymbol{\theta}}}$$

The General Linear Model (GLM)

$$Y_t = \mathbf{x}_t^T \boldsymbol{\theta} + \varepsilon_t$$

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Is this model a GLM?

$$Y_t = \theta_0 + \theta_1 z_t + \varepsilon_t$$

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Yes, what about this one?

$$Y_t = \theta_0 + \theta_1 z_t + \theta_2 z_t^2 + \varepsilon_t$$

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Also yes, since it can be written as

$$y_t = \begin{pmatrix} 1 & z_t & z_t^2 \end{pmatrix} \begin{pmatrix} \theta_0 \\ \theta_1 \\ \theta_2 \end{pmatrix} + \varepsilon_t$$

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$$y_t = \begin{pmatrix} 1 & z_t & z_t^2 \end{pmatrix} \begin{pmatrix} \theta_0 \\ \theta_1 \\ \theta_2 \end{pmatrix} + \varepsilon_t$$

It is linearity in the parameters that matters!

Matrix notation

For all observations the model equations are written as:

$$\begin{bmatrix} Y_1 \\ \vdots \\ Y_n \end{bmatrix} = \begin{bmatrix} \mathbf{x}_1^T \\ \vdots \\ \mathbf{x}_n^T \end{bmatrix} \boldsymbol{\theta} + \begin{bmatrix} \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{bmatrix} \quad \text{or} \quad \mathbf{Y} = \mathbf{x}\boldsymbol{\theta} + \boldsymbol{\varepsilon}$$

"Design
Matrix"

Matrix notation

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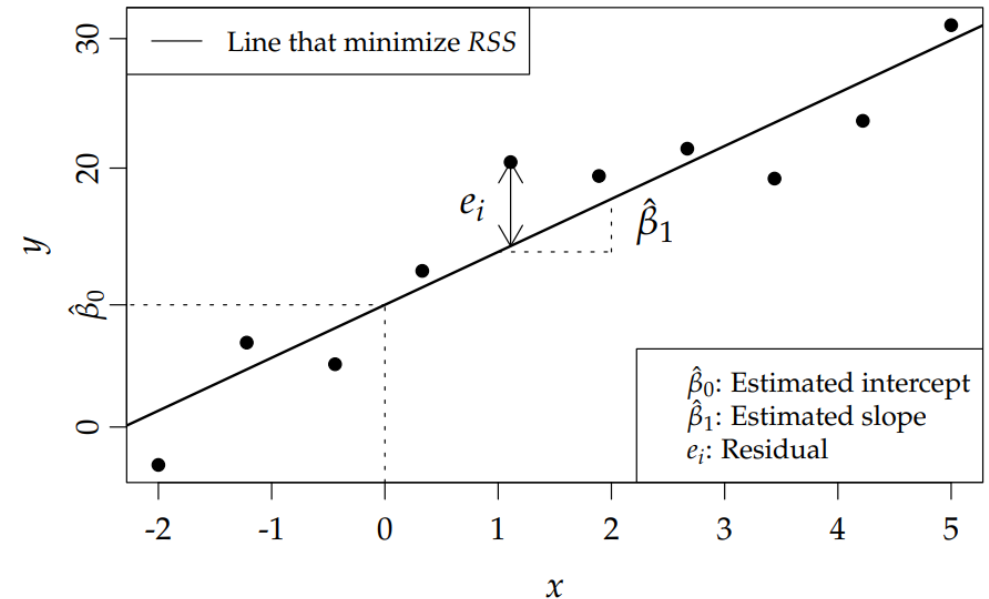
$$\begin{bmatrix} Y_1 \\ \vdots \\ Y_n \end{bmatrix} = \begin{bmatrix} \mathbf{x}_1^T \\ \vdots \\ \mathbf{x}_n^T \end{bmatrix} \boldsymbol{\theta} + \begin{bmatrix} \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{bmatrix} \quad \text{or} \quad \mathbf{Y} = \mathbf{X}\boldsymbol{\theta} + \boldsymbol{\varepsilon}$$

"Design Matrix"

Ex: Simple linear regression:

$$Y_i = \beta_0 + \beta_1 x_i + \varepsilon_i, \quad i = \{1, \dots, n\}$$

$$\begin{bmatrix} Y_1 \\ \vdots \\ Y_n \end{bmatrix} = \begin{bmatrix} 1 & x_1 \\ \vdots & \vdots \\ 1 & x_n \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \end{bmatrix} + \begin{bmatrix} \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{bmatrix}$$



OLS estimates for the general linear model

We minimise $S(\boldsymbol{\theta}) = \boldsymbol{\varepsilon}^T \boldsymbol{\varepsilon} = (\mathbf{Y} - \mathbf{x}\boldsymbol{\theta})^T (\mathbf{Y} - \mathbf{x}\boldsymbol{\theta})$, by solving $\frac{\partial}{\partial \boldsymbol{\theta}} S(\hat{\boldsymbol{\theta}}) = 0$.

$$S(\boldsymbol{\theta}) = (\mathbf{Y} - \mathbf{x}\boldsymbol{\theta})^T (\mathbf{Y} - \mathbf{x}\boldsymbol{\theta})$$

$$\nabla_{\boldsymbol{\theta}} S(\boldsymbol{\theta}) = -2\mathbf{x}^T (\mathbf{Y} - \mathbf{x}\boldsymbol{\theta}) = 0$$

$$\mathbf{x}^T \mathbf{x}\boldsymbol{\theta} = \mathbf{x}^T \mathbf{Y}$$

The solution is $\hat{\boldsymbol{\theta}} = (\mathbf{x}^T \mathbf{x})^{-1} \mathbf{x}^T \mathbf{Y}$

OLS estimates for the general linear model

Point estimate of parameters:

$$\hat{\boldsymbol{\theta}} = (\mathbf{x}^T \mathbf{x})^{-1} \mathbf{x}^T \mathbf{Y}$$

Variance of parameters:

$$\text{Var}[\hat{\boldsymbol{\theta}}] = \text{E} \left[(\hat{\boldsymbol{\theta}} - \boldsymbol{\theta})(\hat{\boldsymbol{\theta}} - \boldsymbol{\theta})^T \right] = \sigma^2 (\mathbf{x}^T \mathbf{x})^{-1}$$

Or approximately:

$$V[\hat{\boldsymbol{\theta}}] = 2\hat{\sigma}^2 \left[\frac{\partial^2}{\partial^2 \boldsymbol{\theta}} S(\boldsymbol{\theta}) \right]^{-1} \Big|_{\boldsymbol{\theta}=\hat{\boldsymbol{\theta}}}$$

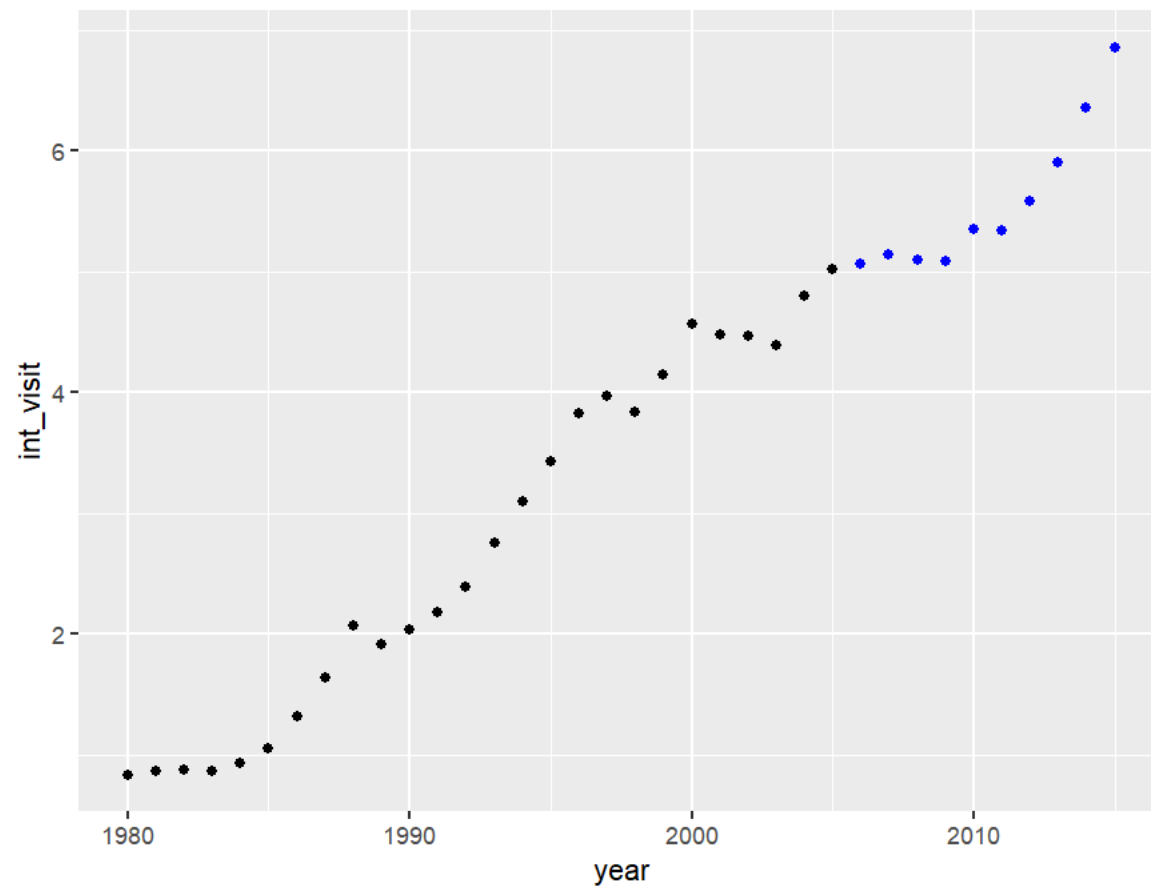
Estimate of the variance of residuals:

$$\hat{\sigma}^2 = \boldsymbol{\varepsilon}^T \boldsymbol{\varepsilon} / (n - p)$$

Properties of the OLS-estimator of a GLM

- ▶ It is a linear function of the observations \mathbf{Y} (and $\widehat{\mathbf{Y}}$ is thus a linear function of the observations)
- ▶ It is unbiased, i.e. $E[\widehat{\boldsymbol{\theta}}] = \boldsymbol{\theta}$
- ▶ $V[\widehat{\boldsymbol{\theta}}] = E[(\widehat{\boldsymbol{\theta}} - \boldsymbol{\theta})(\widehat{\boldsymbol{\theta}} - \boldsymbol{\theta})^T] = \sigma^2(\mathbf{x}^T \mathbf{x})^{-1}$
- ▶ $\widehat{\boldsymbol{\theta}}$ is BLUE (Best Linear Unbiased Estimator), which means that it has the smallest variance among all estimators which are a linear function of the observations.

Example in R



Example in R

```
> print(X)
  [,1] [,2]
[1,]  1 1980
[2,]  1 1981
[3,]  1 1982
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```
> print(y)
  [,1]
[1,] 0.8298943
[2,] 0.8595109
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[23,] 4.4627960
[24,] 4.3848290
[25,] 4.7968610
[26,] 5.0150490
```

$$\hat{\theta} = (x^T x)^{-1} x^T Y$$

```
OLS <- solve(t(X)%*%X)%*%t(X)%*%y
```

```
theta_0 <- OLS[1]
theta_1 <- OLS[2]
```

Parameter estimates

Example in R

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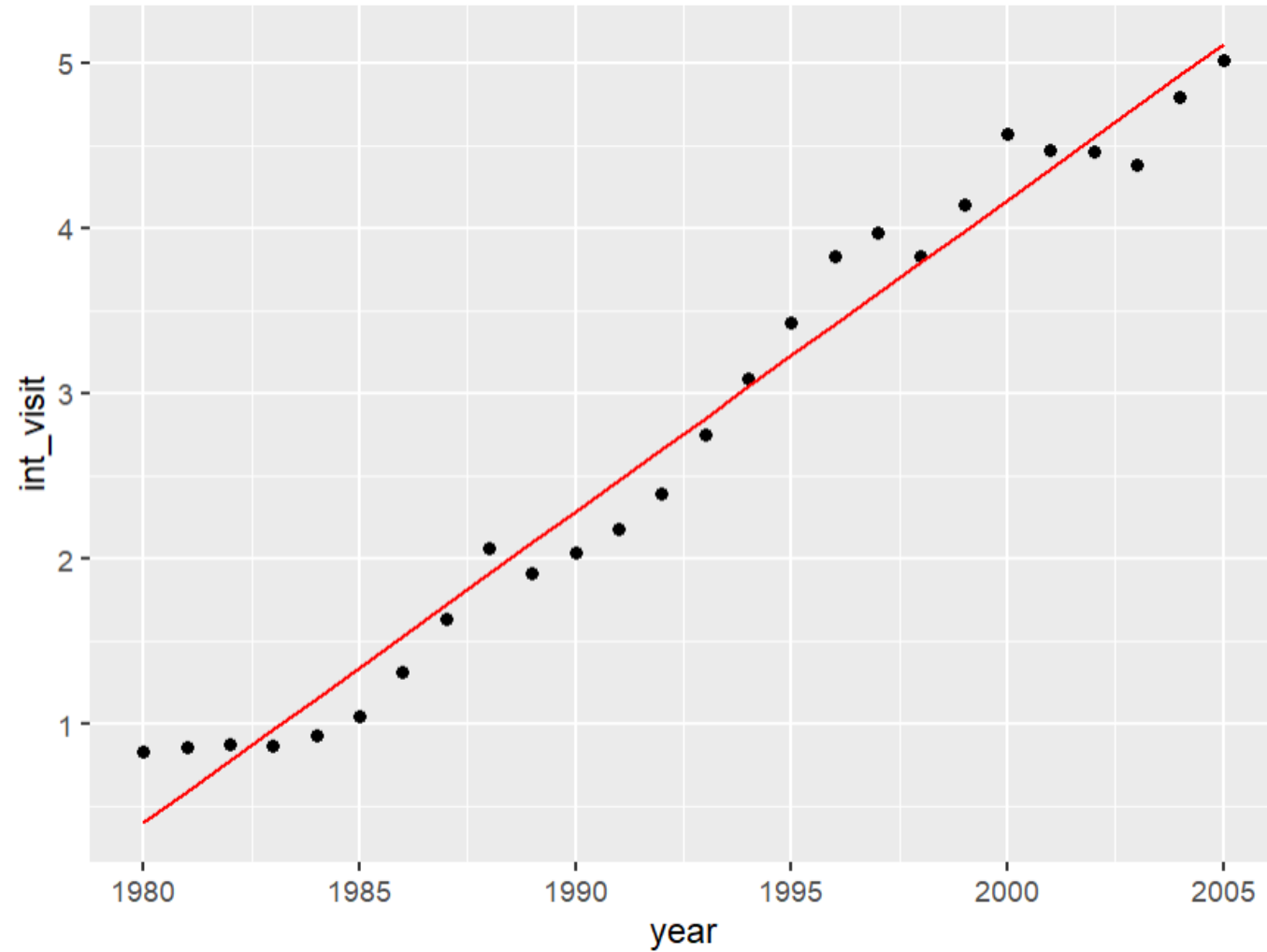
Parameter estimates

$$\hat{Y} = x\hat{\theta}$$

```
yhat_ols <- X%*%OLS
```

Predicted values

Example in R



Example in R

```
e_ols <- y - yhat_ols
```

```
RSS_ols <- t(e_ols)%*%e_ols
```

```
sigma2_ols <- as.numeric(RSS_ols/(n - nparams))
```

```
V_ols <- sigma2_ols * solve(t(X) %*% X)
```

```
> print(V_ols)
      [,1]      [,2]
[1,] 165.6609970 -8.314110e-02
[2,] -0.0831411  4.172703e-05
```

```
se_theta_0 <- (sqrt(diag(V_ols)))[1]
se_theta_1 <- (sqrt(diag(V_ols)))[2]
```

$$\hat{\sigma}^2 = \boldsymbol{\varepsilon}^T \boldsymbol{\varepsilon} / (n - p)$$

$$\text{Var}[\hat{\boldsymbol{\theta}}] = \text{E} \left[(\hat{\boldsymbol{\theta}} - \boldsymbol{\theta})(\hat{\boldsymbol{\theta}} - \boldsymbol{\theta})^T \right] = \sigma^2 (\mathbf{x}^T \mathbf{x})^{-1}$$

Now we have estimated the parameters
AND their standard error

Outline of the lecture

- Regression based methods, 1st part:
 - Ordinary Least Squares (OLS)
 - **Predictions = forecast**
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 -

Prediction in the general linear model

If the expected value of the squared prediction error is to be minimized, then the expected mean $E[Y|\mathbf{X} = \mathbf{x}]$ is the optimal predictor.

$$Y_t = \mathbf{x}_t^T \boldsymbol{\theta} + \varepsilon_t$$

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Known parameters:

$$\hat{Y}_t = E_{\theta}[Y_t | \mathbf{X}_t = \mathbf{x}_t] = \mathbf{x}_t^T \boldsymbol{\theta}$$

$$V_{\theta}[Y_t - \hat{Y}_t] = V_{\theta}[\varepsilon_t] = \sigma^2$$

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$$V_{\theta}[Y_t - \hat{Y}_t] = V_{\theta}[\varepsilon_t] = \sigma^2$$

Estimated parameters:

$$\hat{Y}_t = E_{\hat{\theta}}[Y_t | \mathbf{X}_t = \mathbf{x}_t] = \mathbf{x}_t^T \hat{\boldsymbol{\theta}}$$

$$V_{\hat{\theta}}[Y_t - \hat{Y}_t] = V_{\hat{\theta}}[\varepsilon_t + \mathbf{x}_t^T (\boldsymbol{\theta} - \hat{\boldsymbol{\theta}})] = \hat{\sigma}^2 [1 + \mathbf{x}_t^T (\mathbf{x}^T \mathbf{x})^{-1} \mathbf{x}_t]$$

Prediction in the general linear model, continued

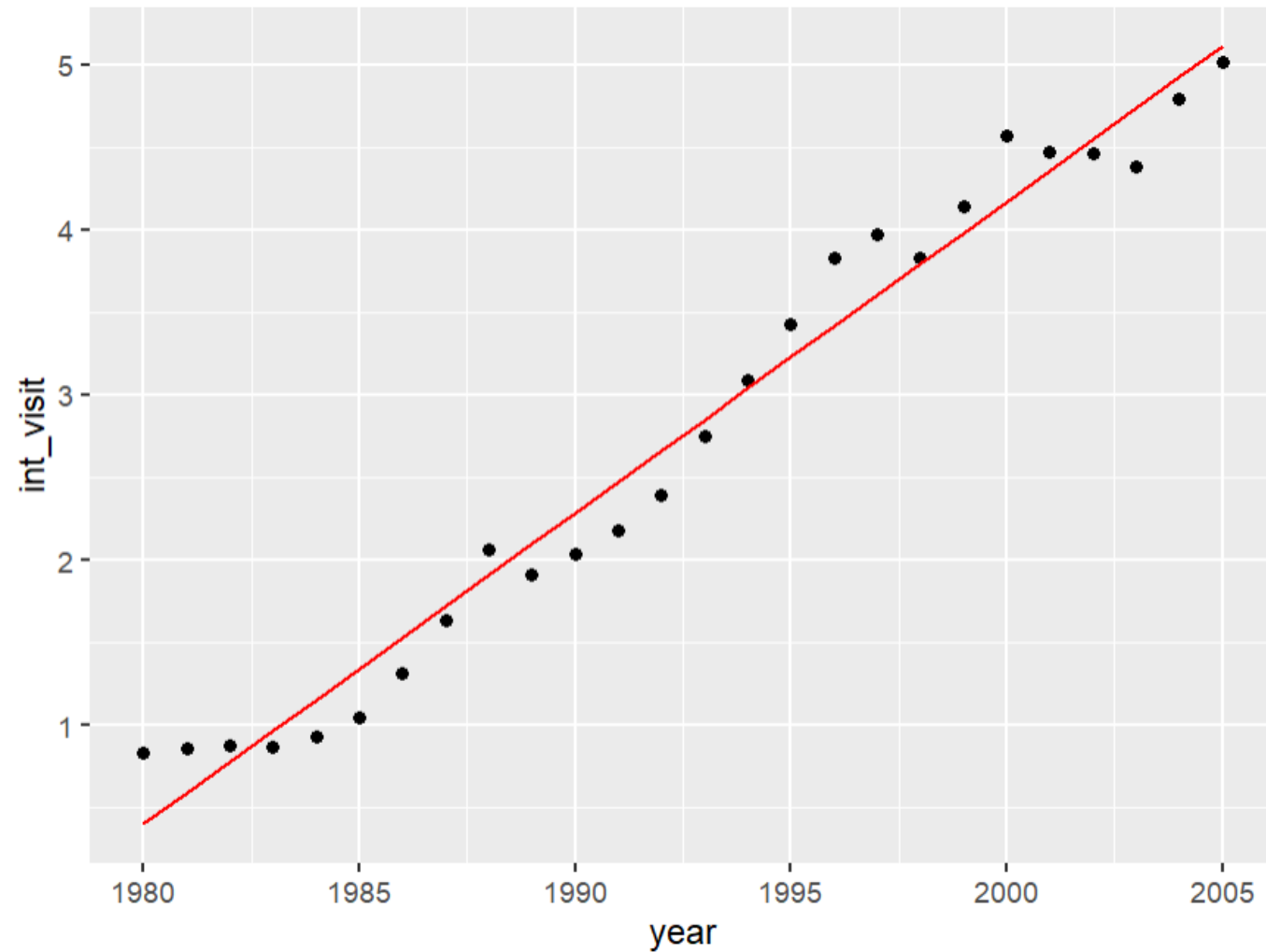
Prediction interval for the predicted values:

$$\hat{Y}_t \pm t_{\alpha/2}(n - p)\hat{\sigma}\sqrt{1 + \mathbf{x}_t^T(\mathbf{x}^T\mathbf{x})^{-1}\mathbf{x}_t}$$

Here $t_{\alpha/2}(n - p)$ refers to a percentile in the t-distribution with $n-p$ degrees of freedom. If $n-p$ is large, percentiles from the normal distribution can be used.

In time series analysis: Prediction of future values = **"forecast"**

Example in R



Lets make predictions
(forecast) for the next
10 years

Example in R

```
> print(Xtest)
      [,1] [,2]
[1,]    1 2006
[2,]    1 2007
[3,]    1 2008
[4,]    1 2009
[5,]    1 2010
[6,]    1 2011
[7,]    1 2012
[8,]    1 2013
[9,]    1 2014
[10,]   1 2015
```

$$\hat{Y}_t = E_{\hat{\theta}}[Y_t | \mathbf{X}_t = \mathbf{x}_t] = \mathbf{x}_t^T \hat{\boldsymbol{\theta}}$$

```
y_pred <- Xtest%*%OLS
```

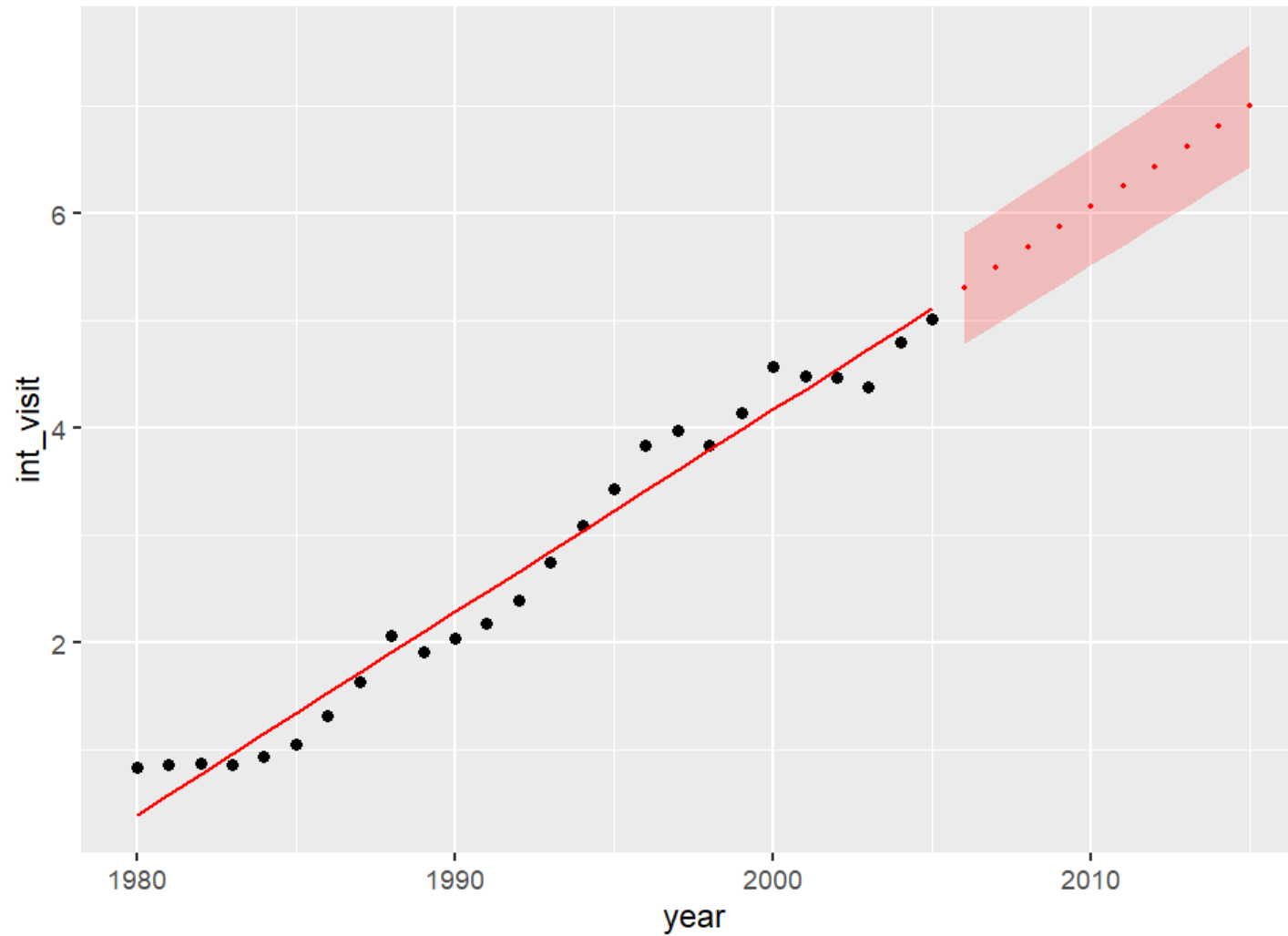
$$\hat{\sigma}^2 [1 + \mathbf{x}_t^T (\mathbf{x}^T \mathbf{x})^{-1} \mathbf{x}_t]$$

```
Vmatrix_pred <- sigma2_ols*(1+(Xtest%*%solve(t(X)%*%X))%*%t(Xtest))
```

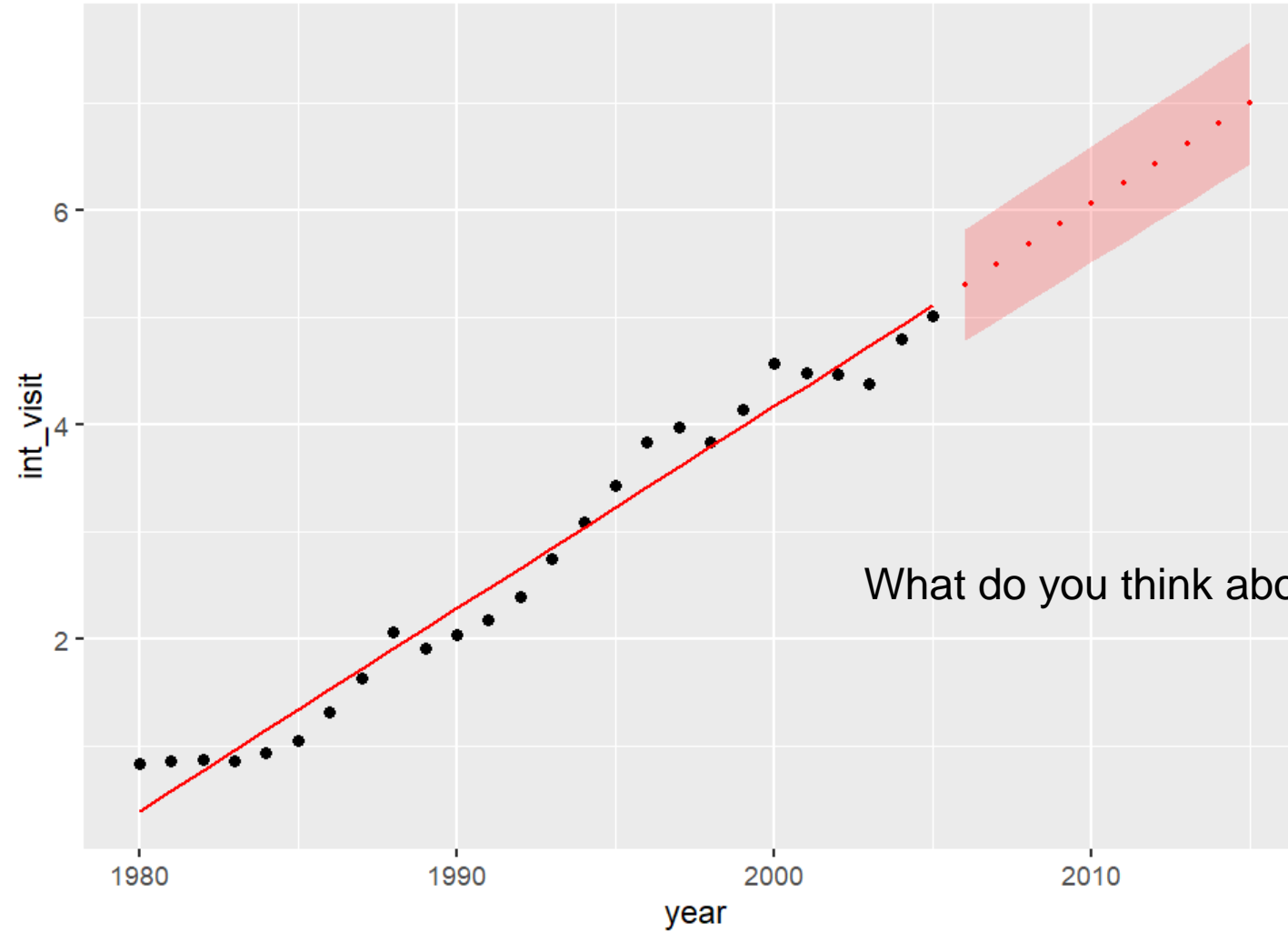
$$\hat{Y}_t \pm t_{\alpha/2}(n - p) \hat{\sigma} \sqrt{1 + \mathbf{x}_t^T (\mathbf{x}^T \mathbf{x})^{-1} \mathbf{x}_t}$$

```
y_pred_lwr <- y_pred - 1.96*sqrt(diag(Vmatrix_pred))
y_pred_upr <- y_pred + 1.96*sqrt(diag(Vmatrix_pred))
```


Example in R

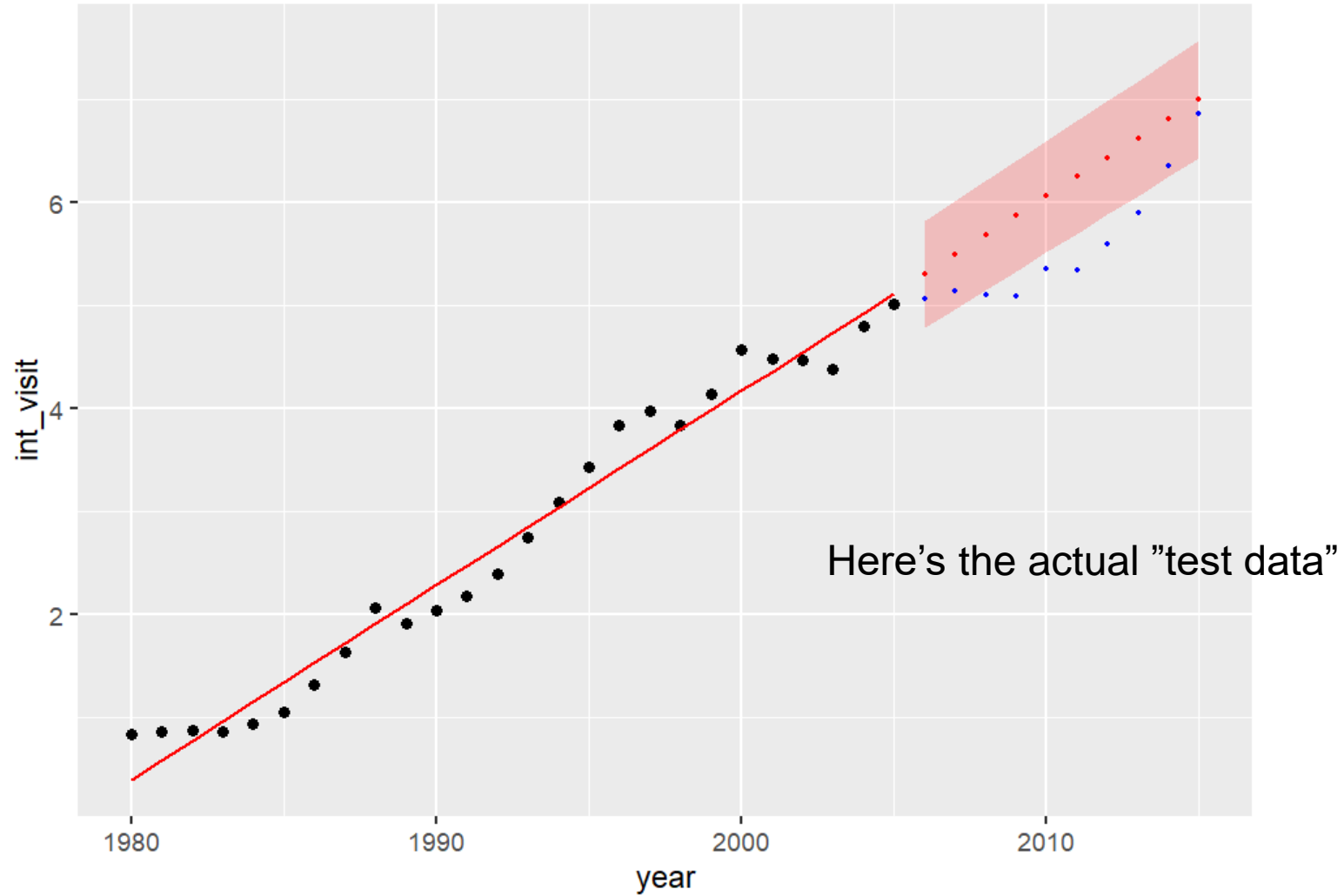


Example in R



What do you think about the forecast?

Example in R



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 - Ordinary Least Squares (OLS)
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 - **Global Trend Model**
 -

Sneakpeak at “Trend Models”

Trend models are:

- Linear regression models
- The independent variables are functions of time
- The reference time is often the latest timepoint instead of the “origin”
- Notation is a bit different – the principle is the same

$$Y_{N+j} = f^T(j)\boldsymbol{\theta} + \varepsilon_{N+j}$$

Today we will only talk about **global** trend models

Sneakpeak at “Trend Models”

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$$Y_{N+j} = f^T(j)\boldsymbol{\theta} + \varepsilon_{N+j}$$

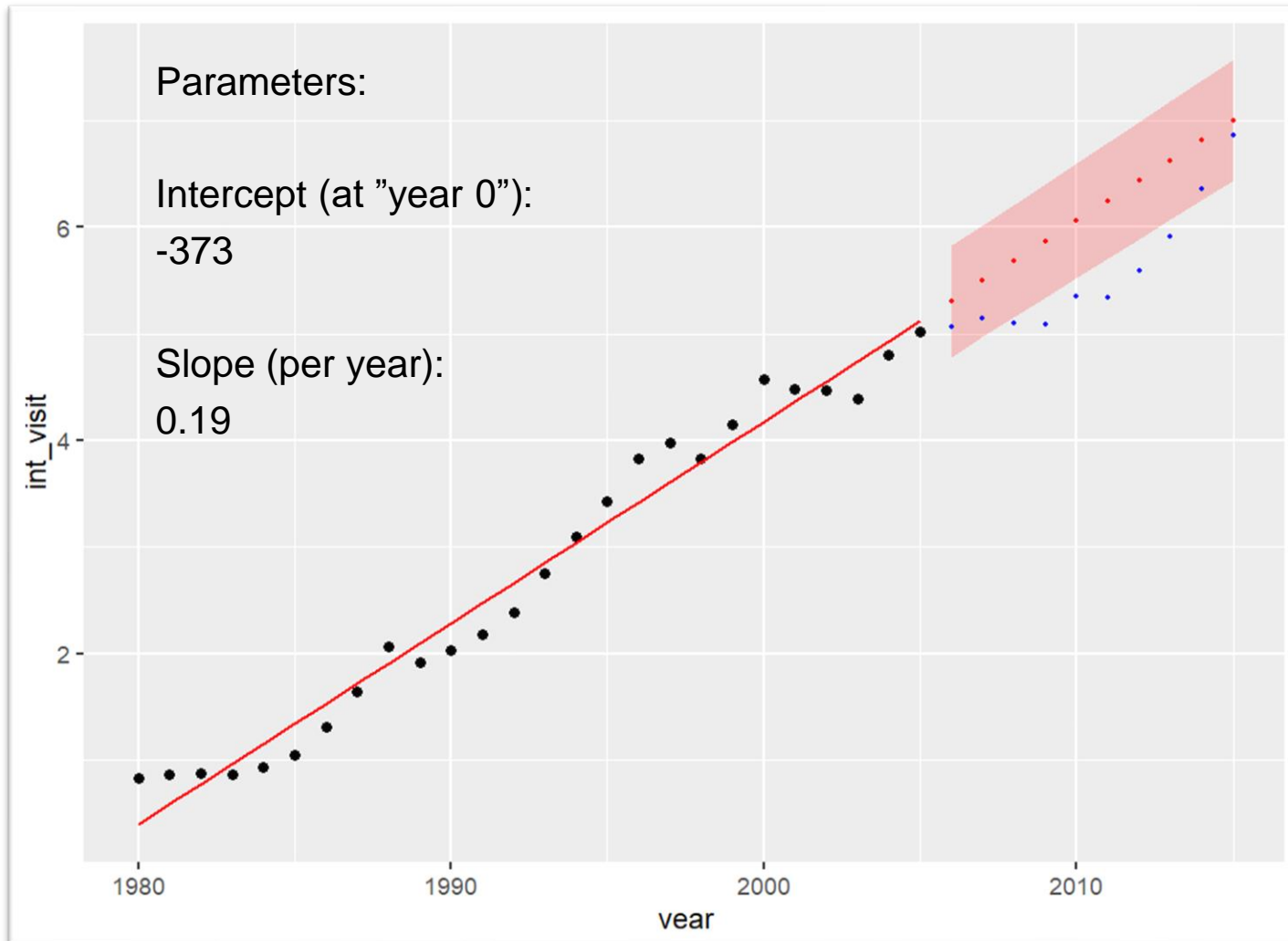
N refers to the “latest” timepoint in the data – this is our reference timepoint (=“now”)

If we put $j=0$, we get the estimate “now”

$j = 1, 2, 3, \dots$ refers to future timepoints

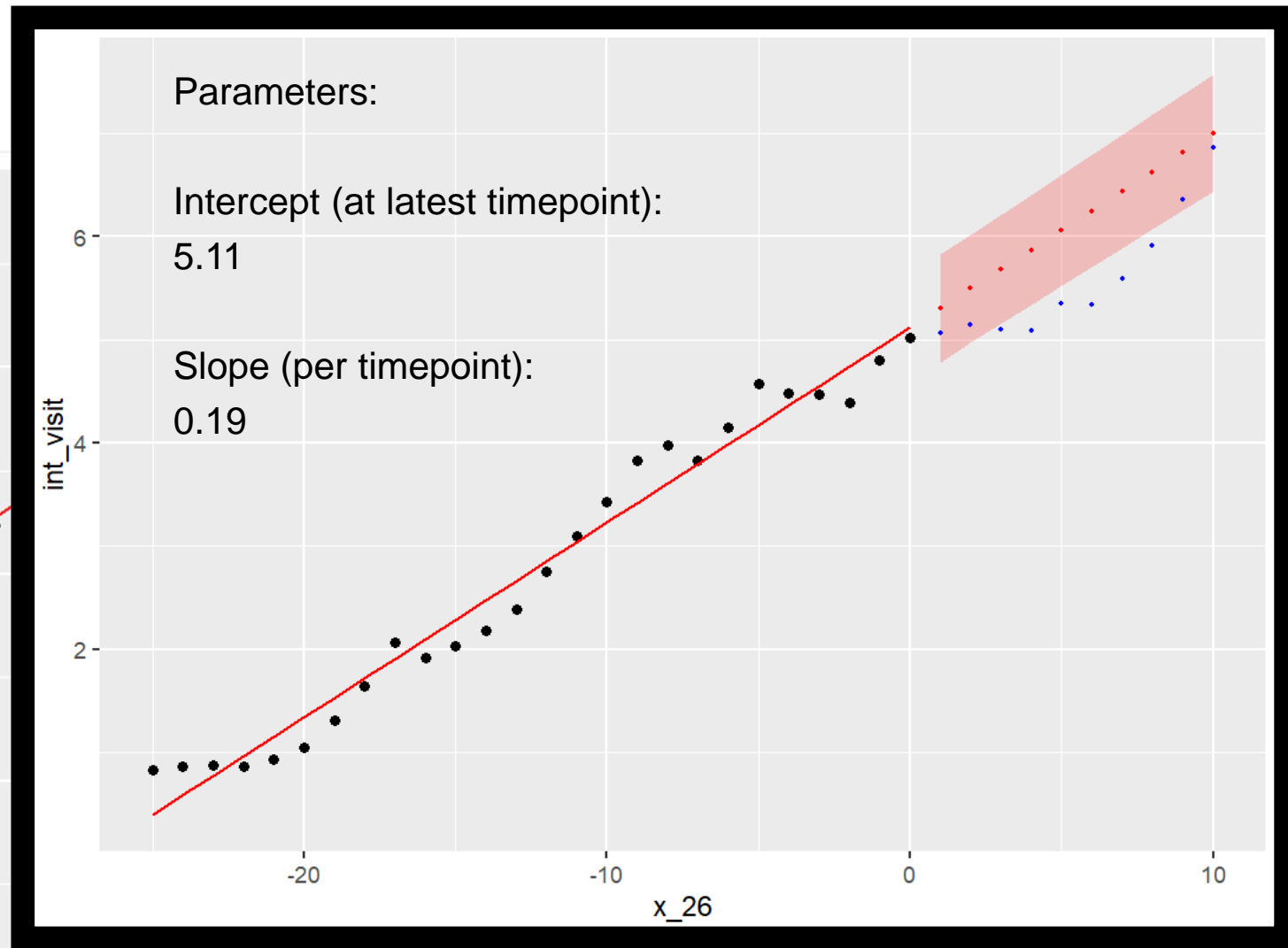
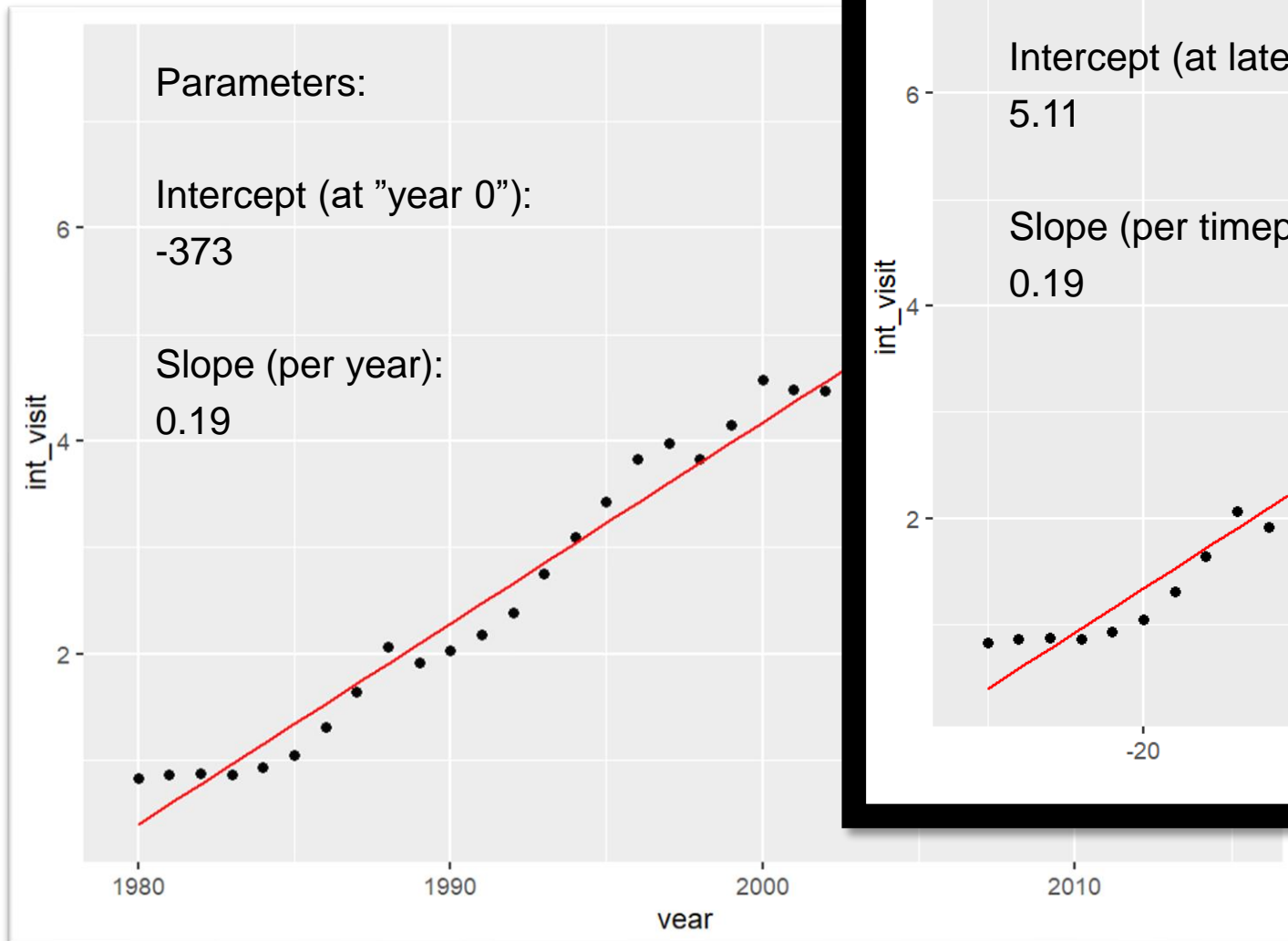
The data available to estimate the model is the data from $j = 0, -1, -2, -3, \dots$

Example in R



Example in R

Trend model setting:



Notice the change in x-axis!
Number of obs. in training data = $N = 26c$

The linear trend model

- ▶ The general trend model:

$$Y_{N+j} = \mathbf{f}^T(j)\boldsymbol{\theta} + \varepsilon_{N+j}$$

- ▶ The linear trend model is obtained when: $\mathbf{f}(j) = \begin{pmatrix} 1 \\ j \end{pmatrix}$

$$\begin{bmatrix} Y_1 \\ Y_2 \\ \vdots \\ Y_N \end{bmatrix} = \begin{bmatrix} \mathbf{f}^T(-N+1) \\ \mathbf{f}^T(-N+2) \\ \vdots \\ \mathbf{f}^T(0) \end{bmatrix} \boldsymbol{\theta}_N + \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \vdots \\ \varepsilon_N \end{bmatrix}$$

Example in R

```
> print(X)
  [,1] [,2]
[1,]  1 1980
[2,]  1 1981
[3,]  1 1982
[4,]  1 1983
[5,]  1 1984
[6,]  1 1985
[7,]  1 1986
[8,]  1 1987
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[17,] 1 1996
[18,] 1 1997
[19,] 1 1998
[20,] 1 1999
[21,] 1 2000
[22,] 1 2001
[23,] 1 2002
[24,] 1 2003
[25,] 1 2004
[26,] 1 2005
```

"Design-
Matrix"
changes



```
> print(X_N)
  [,1] [,2]
[1,]  1 -25
[2,]  1 -24
[3,]  1 -23
[4,]  1 -22
[5,]  1 -21
[6,]  1 -20
[7,]  1 -19
[8,]  1 -18
[9,]  1 -17
[10,] 1 -16
[11,] 1 -15
[12,] 1 -14
[13,] 1 -13
[14,] 1 -12
[15,] 1 -11
[16,] 1 -10
[17,]  1  -9
[18,]  1  -8
[19,]  1  -7
[20,]  1  -6
[21,]  1  -5
[22,]  1  -4
[23,]  1  -3
[24,]  1  -2
[25,]  1  -1
[26,]  1   0
```

Vector of y-values
stays the same

```
> print(y)
  [,1]
[1,] 0.8298943
[2,] 0.8595109
[3,] 0.8766892
[4,] 0.8667072
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```

Trend model, OLS estimates

$$\begin{aligned}
 \mathbf{Y}_N &= \mathbf{x}_N \boldsymbol{\theta}_N + \boldsymbol{\varepsilon} \\
 \begin{bmatrix} Y_1 \\ Y_2 \\ \vdots \\ Y_N \end{bmatrix} &= \begin{bmatrix} \mathbf{f}^T(-N+1) \\ \mathbf{f}^T(-N+2) \\ \vdots \\ \mathbf{f}^T(0) \end{bmatrix} \boldsymbol{\theta}_N + \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \vdots \\ \varepsilon_N \end{bmatrix}
 \end{aligned}$$

$$\hat{\boldsymbol{\theta}}_N = (\mathbf{x}_N^T \mathbf{x}_N)^{-1} \mathbf{x}_N^T \mathbf{Y}_N = \mathbf{F}_N^{-1} \mathbf{h}_N$$

$$\mathbf{F}_N = \mathbf{x}_N^T \mathbf{x}_N = \sum_{j=0}^{N-1} \mathbf{f}(-j) \mathbf{f}^T(-j)$$

$$\mathbf{h}_N = \mathbf{x}_N^T \mathbf{Y} = \sum_{j=0}^{N-1} \mathbf{f}(-j) Y_{N-j}$$

It is still an OLS regression model!

The notation is different

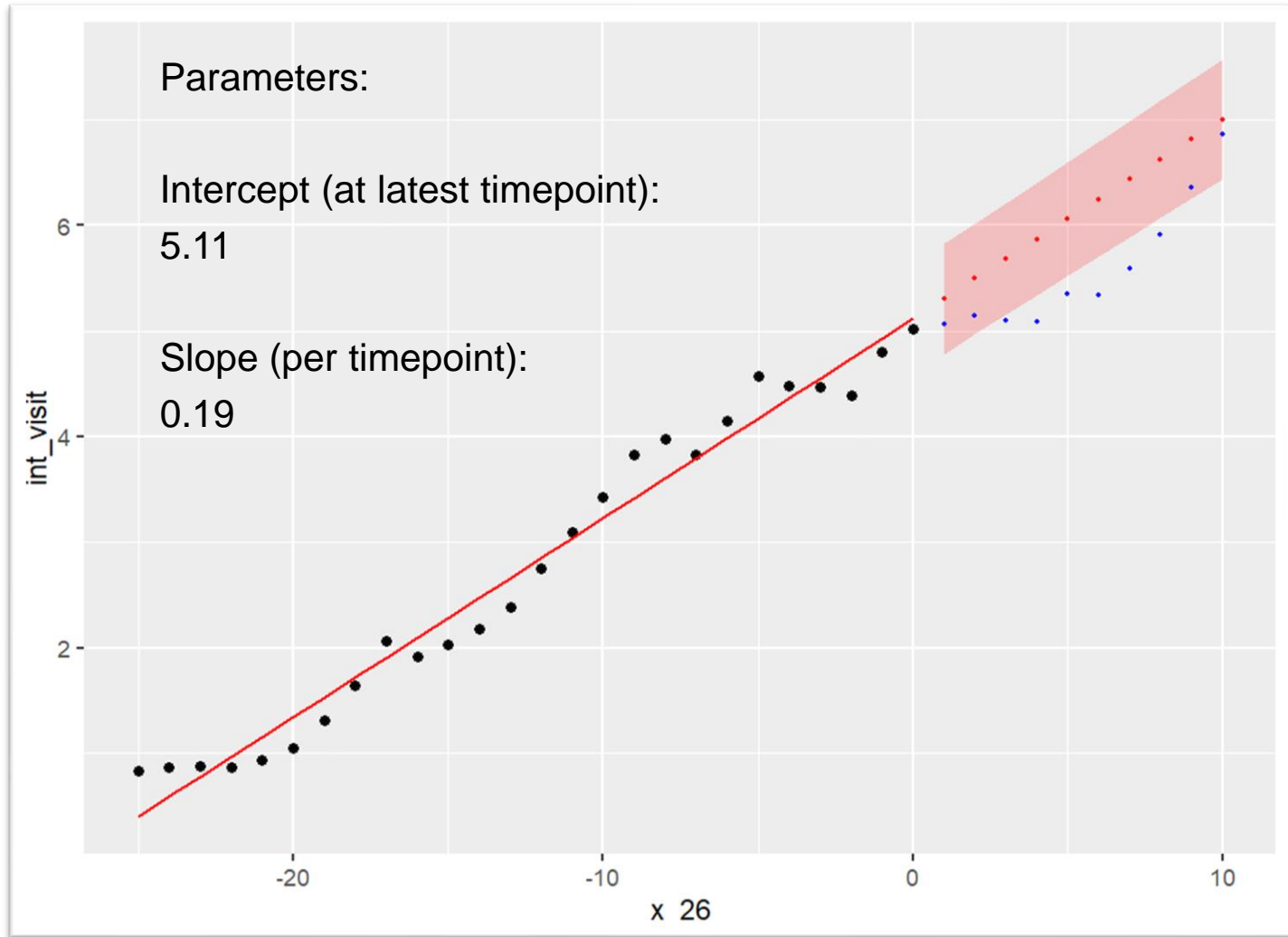
Example in R

Estimating the parameters:

```
F_N <- t(X_N)%*%X_N
```

```
h_N <- t(X_N)%*%y
```

```
theta_N <- solve(F_N)%*%h_N  
print(theta_N)  
# [1,] 5.115330  
# [2,] 0.188649
```



Other trend models

- ▶ Constant mean: $Y_{N+j} = \theta_0 + \varepsilon_{N+j}$
- ▶ Linear trend: $Y_{N+j} = \theta_0 + \theta_1 j + \varepsilon_{N+j}$
- ▶ Quadratic trend: $Y_{N+j} = \theta_0 + \theta_1 j + \theta_2 \frac{j^2}{2} + \varepsilon_{n+j}$
- ▶ k 'th order polynomial trend: $Y_{n+j} = \theta_0 + \theta_1 j + \theta_2 \frac{j^2}{2} + \dots + \theta_k \frac{j^k}{k!} + \varepsilon_{N+j}$
- ▶ Harmonic model with the period p : $Y_{N+j} = \theta_0 + \theta_1 \sin \frac{2\pi}{p} j + \theta_2 \cos \frac{2\pi}{p} j + \varepsilon_{N+j}$

Trend model forecasting (“ ℓ -step predictions”)

- ▶ Prediction:

$$\hat{Y}_{N+\ell|N} = \mathbf{f}^T(\ell) \hat{\boldsymbol{\theta}}_N$$

- ▶ Variance of the prediction error:

$$V[Y_{N+\ell} - \hat{Y}_{N+\ell|N}] = \sigma^2 [1 + \mathbf{f}^T(\ell) \mathbf{F}_N^{-1} \mathbf{f}(\ell)]$$

- ▶ 100(1 - α)% prediction interval:

$$\begin{aligned} & \hat{Y}_{N+\ell|N} \pm t_{\alpha/2}(N-p) \sqrt{V[e_N(\ell)]} \\ &= \hat{Y}_{N+\ell|N} \pm t_{\alpha/2}(N-p) \hat{\sigma} \sqrt{1 + \mathbf{f}^T(\ell) \mathbf{F}_N^{-1} \mathbf{f}(\ell)} \end{aligned}$$

where $\hat{\sigma}^2 = \boldsymbol{\varepsilon}^T \boldsymbol{\varepsilon} / (N - p)$ (p is the number of estimated parameters)

Example in R

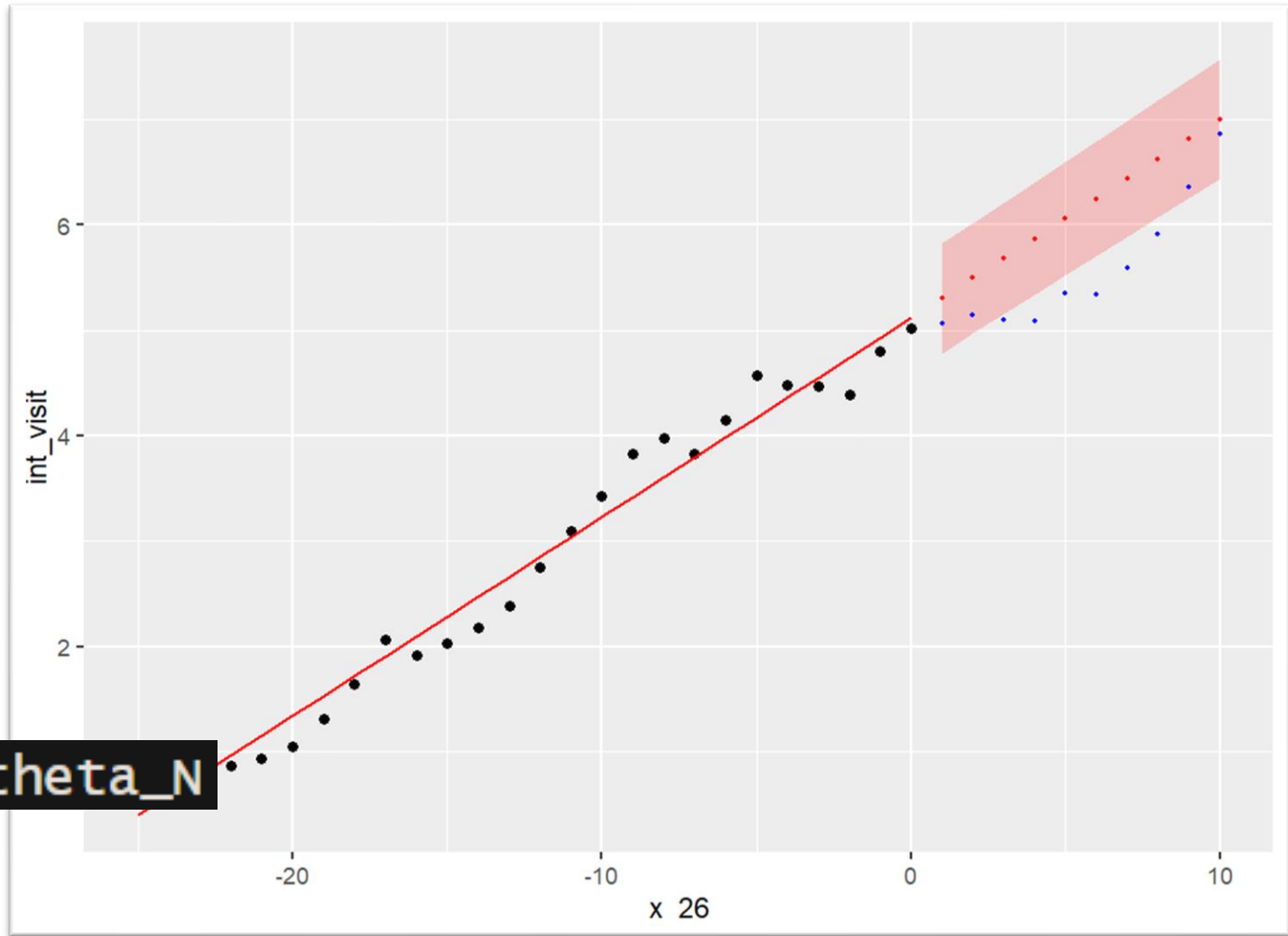
Predicting the future values
(here we predict for $j = 1, 2, 3, 4, 5, 6, 7, 8, 9, 10$)

$$f(j) = \begin{pmatrix} 1 \\ j \end{pmatrix}$$

```
f <- function(j) rbind(1, j)
```

$$\hat{Y}_{N+\ell|N} = f^T(\ell) \hat{\theta}_N$$

```
y_pred_N <- t(f(1:10)) %*% theta_N
```



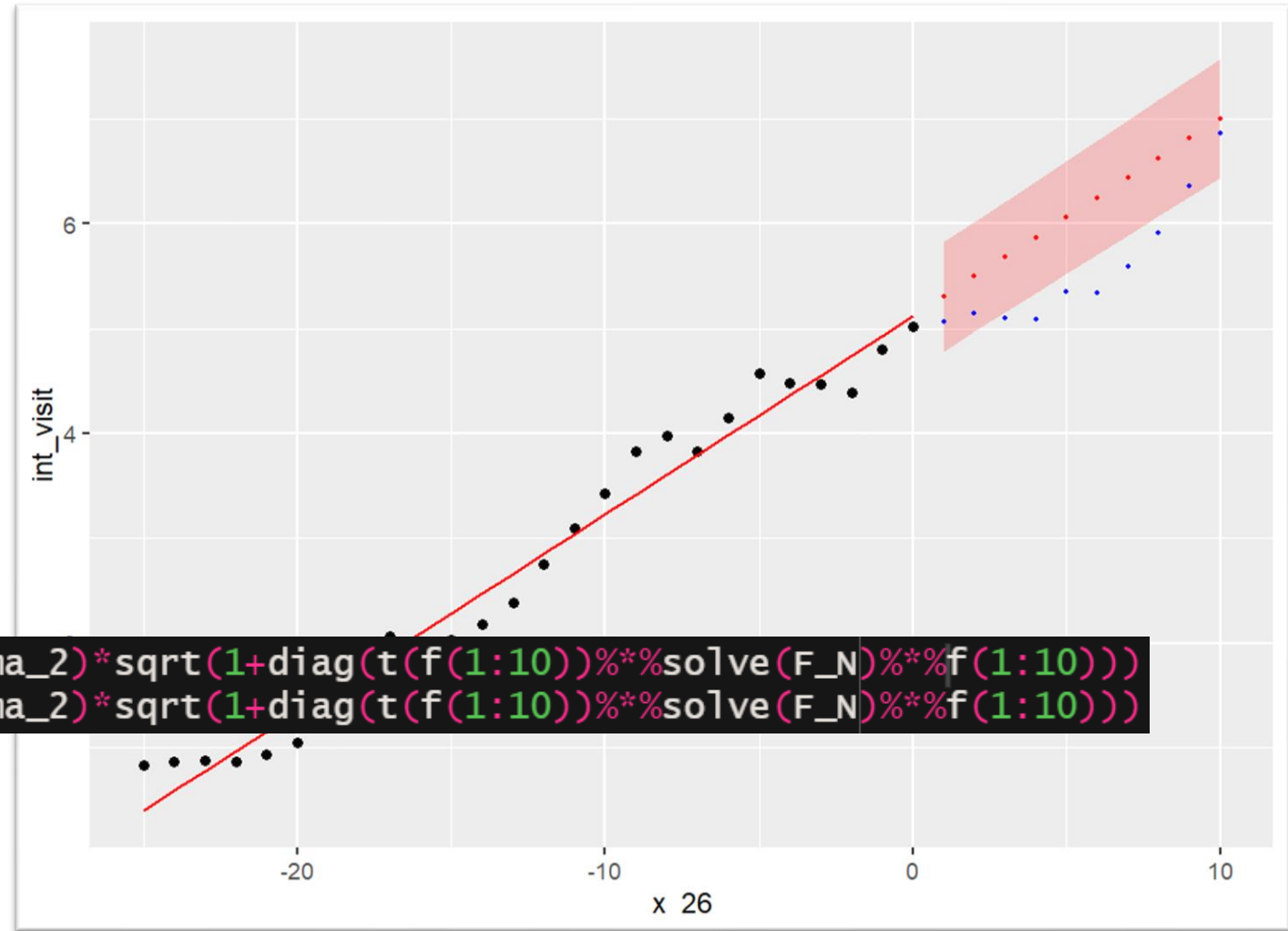
Example in R

Compute prediction intervals

$$\hat{Y}_{N+\ell|N} \pm t_{\alpha/2}(N - p)\hat{\sigma}\sqrt{1 + \mathbf{f}^T(\ell)\mathbf{F}_N^{-1}\mathbf{f}(\ell)}$$

```
e_N <- y - yhat_N
RSS <- t(e_N)%*%e_N
sigma_2 <- as.numeric(RSS/(n-nparams))
```

```
y_pred_N_lwr <- y_pred_N - 1.96*sqrt(sigma_2)*sqrt(1+diag(t(f(1:10))%*%solve(F_N)%*%f(1:10)))
y_pred_N_upr <- y_pred_N + 1.96*sqrt(sigma_2)*sqrt(1+diag(t(f(1:10))%*%solve(F_N)%*%f(1:10)))
```



Why do all this ??

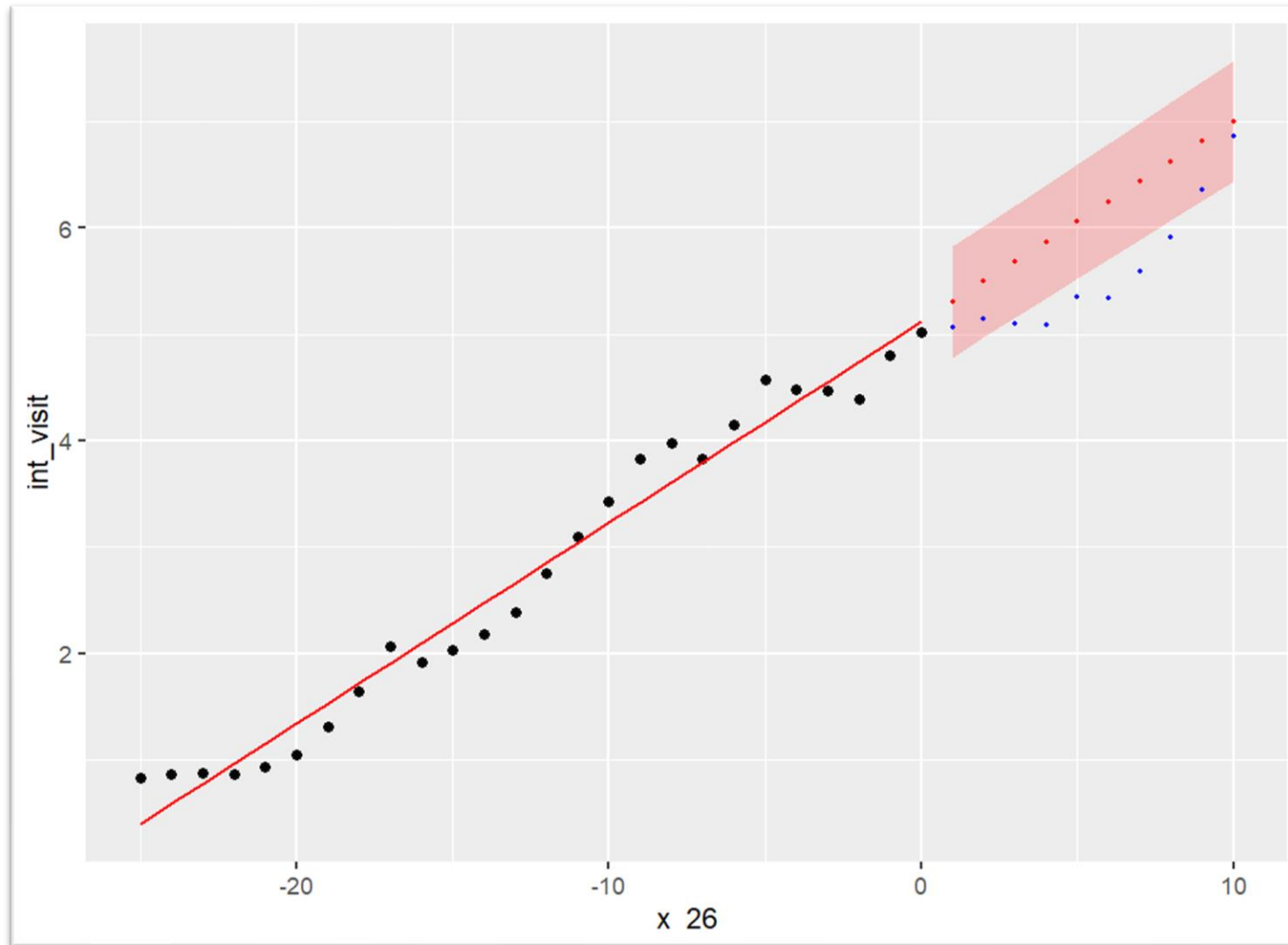
Iterative updates

- ▶ Task:
 - ▶ Going from estimates based on $t = 1, \dots, N$, i.e. $\hat{\boldsymbol{\theta}}_N$ to
 - ▶ estimates based on $t = 1, \dots, N, N + 1$, i.e. $\hat{\boldsymbol{\theta}}_{N+1}$
 - ▶ without redoing everything...
- ▶ Solution:

$$\begin{aligned}\mathbf{F}_{N+1} &= \mathbf{F}_N + \mathbf{f}(-N)\mathbf{f}^T(-N) \\ \mathbf{h}_{N+1} &= \mathbf{L}^{-1}\mathbf{h}_N + \mathbf{f}(0)Y_{N+1} \\ \hat{\boldsymbol{\theta}}_{N+1} &= \mathbf{F}_{N+1}^{-1}\mathbf{h}_{N+1}\end{aligned}$$

Also iterative updates becomes smart, when we start doing **local** trend models (next week)

Update the model,



We get the next observation

We want to shift the x-axis to the latest observation

And redo the regression line

And redo the forecast

Updating the model

$$\begin{aligned} \mathbf{F}_{N+1} &= \mathbf{F}_N + \mathbf{f}(-N)\mathbf{f}^T(-N) \\ \mathbf{h}_{N+1} &= \mathbf{L}^{-1}\mathbf{h}_N + \mathbf{f}(0)Y_{N+1} \\ \hat{\boldsymbol{\theta}}_{N+1} &= \mathbf{F}_{N+1}^{-1}\mathbf{h}_{N+1} \end{aligned}$$

\mathbf{L} defines the transition from $\mathbf{f}(j)$ to $\mathbf{f}(j+1)$

$$\mathbf{f}(j+1) = \mathbf{L}\mathbf{f}(j)$$

Linear trend model

$$Y_{N+j} = \theta_0 + \theta_1 j + \varepsilon_{N+j}$$

$$\mathbf{L} = \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix}, \quad \mathbf{f}(0) = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

Quadratic trend model

$$Y_{N+j} = \theta_0 + \theta_1 j + \theta_2 \frac{j^2}{2} + \varepsilon_{N+j}$$

$$\mathbf{L} = \begin{pmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1/2 & 1 & 1 \end{pmatrix}, \quad \mathbf{f}(0) = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

L matrix examples

k 'th order polynomial trend

$$Y_{N+j} = \theta_0 + \theta_1 j + \theta_2 \frac{j^2}{2} + \cdots + \theta_k \frac{j^k}{k!} + \varepsilon_{N+j}$$

$$\mathbf{L} = \begin{pmatrix} 1 & 0 & \cdots & 0 \\ 1 & 1 & \cdots & 0 \\ 1/2 & 1 & \cdots & 0 \\ \vdots & \vdots & & \vdots \\ 1/k! & 1/(k-1)! & & 1 \end{pmatrix}, \quad \mathbf{f}(0) = \begin{pmatrix} 1 \\ 0 \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

L matrix examples

Harmonic model with the period p

$$Y_{N+j} = \theta_0 + \theta_1 \sin\left(\frac{2\pi}{p}j\right) + \theta_2 \cos\left(\frac{2\pi}{p}j\right) + \varepsilon_{N+j}$$

$$\mathbf{L} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos\left(\frac{2\pi}{p}\right) & \sin\left(\frac{2\pi}{p}\right) \\ 0 & -\sin\left(\frac{2\pi}{p}\right) & \cos\left(\frac{2\pi}{p}\right) \end{pmatrix}, \quad \mathbf{f}(0) = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$$

Example in R

```
L <- matrix(c(1.,0., 1.,1.),
            byrow=TRUE, nrow=2)
```

```
> print(L)
      [,1] [,2]
[1,]    1    0
[2,]    1    1
```

$$L = \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix}$$

```
F_N_27 <- F_N + f(-n) %*% t(f(-n))
h_N_27 <- Linv %*% h_N + f(0)*ynew
theta_N_27 <- solve(F_N_27)%*%h_N_27
```

```
> print(theta_N_27)
      [,1]
5.2702522
j 0.1867399
```

Slight change from before:

5.11

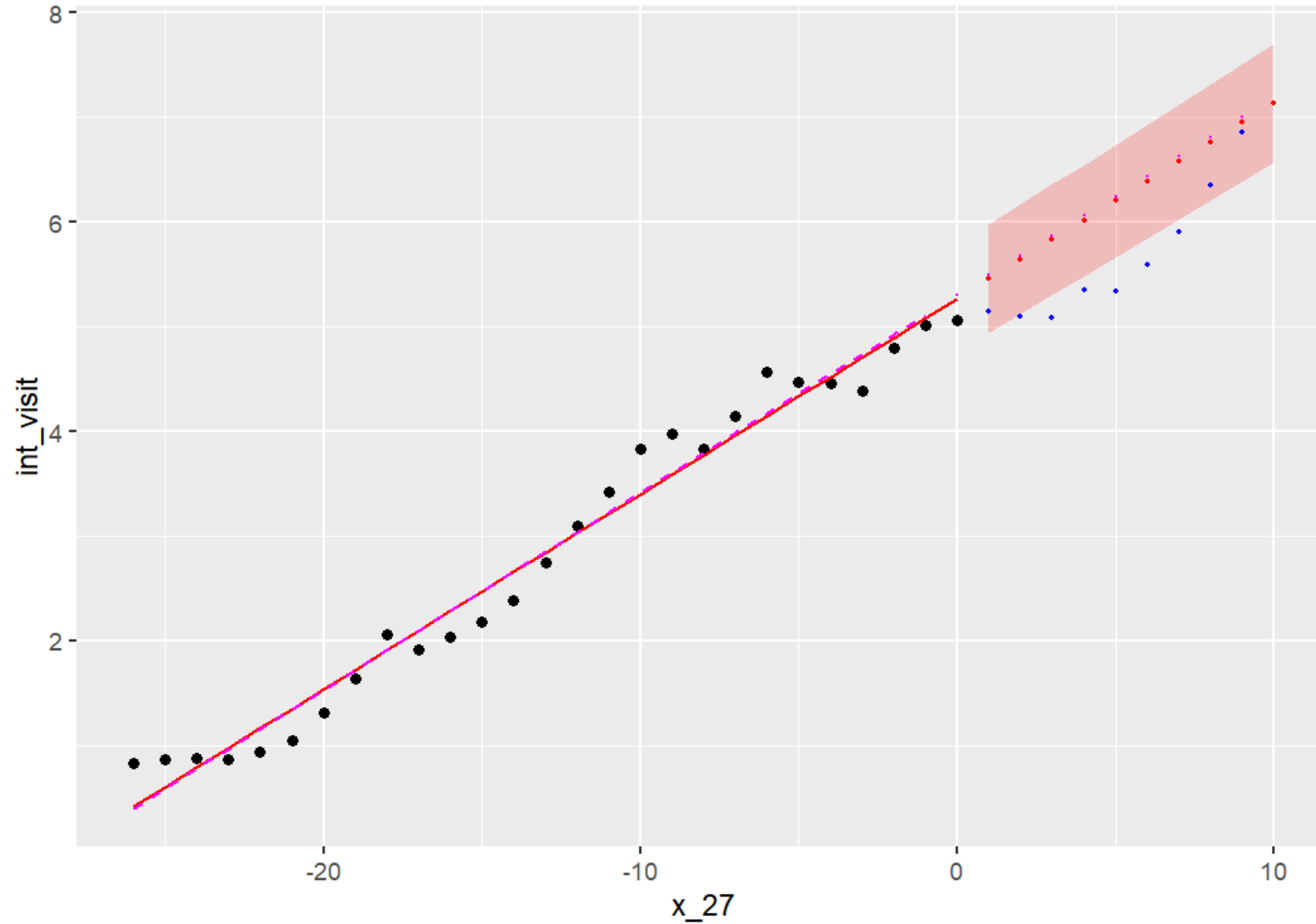
0.19

$$\mathbf{F}_{N+1} = \mathbf{F}_N + \mathbf{f}(-N)\mathbf{f}^T(-N)$$

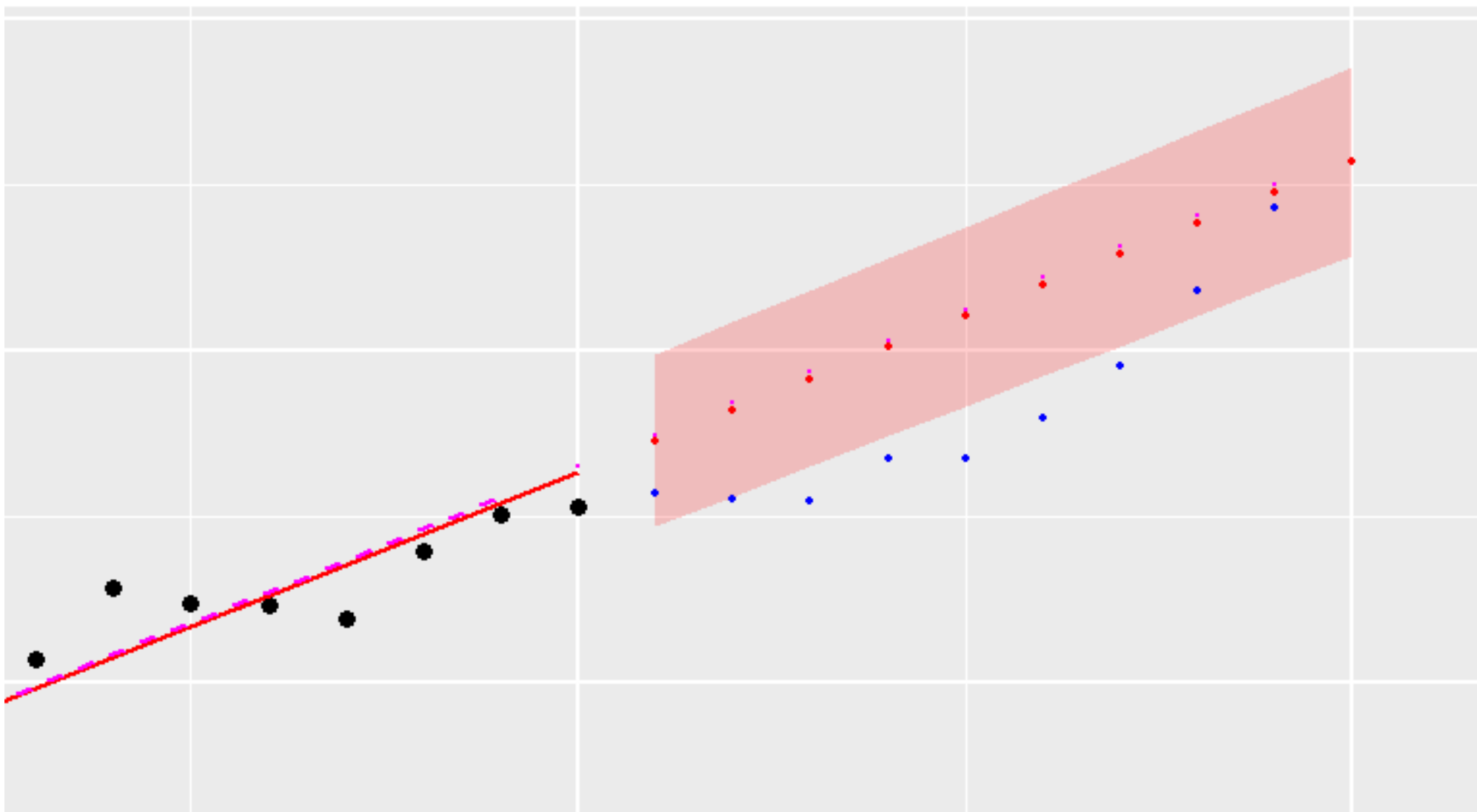
$$\mathbf{h}_{N+1} = \mathbf{L}^{-1}\mathbf{h}_N + \mathbf{f}(0)Y_{N+1}$$

$$\hat{\boldsymbol{\theta}}_{N+1} = \mathbf{F}_{N+1}^{-1}\mathbf{h}_{N+1}$$

Example in R



Example in R



Outline of the lecture

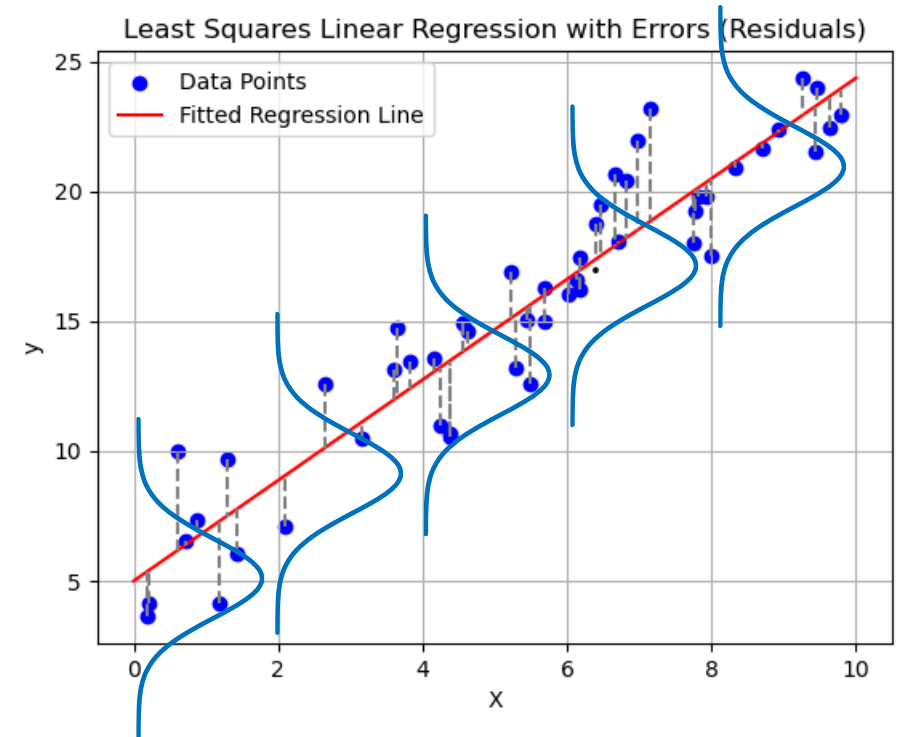
- Regression based methods, 1st part:
 - Ordinary Least Squares (OLS)
 - Predictions = forecast
 - Global Trend Model
 - **Weighted Least Squares (WLS)**

Weighted Least Squares (WLS) estimates

Recall: OLS, minimizing the sum of squared residuals:

$$S(\boldsymbol{\theta}) = \sum_{t=1}^n [y_t - f(\mathbf{x}_t; \boldsymbol{\theta})]^2 = \sum_{t=1}^n \varepsilon_t^2(\boldsymbol{\theta})$$

Where we assumed the residuals have the same variance and are mutually uncorrelated.

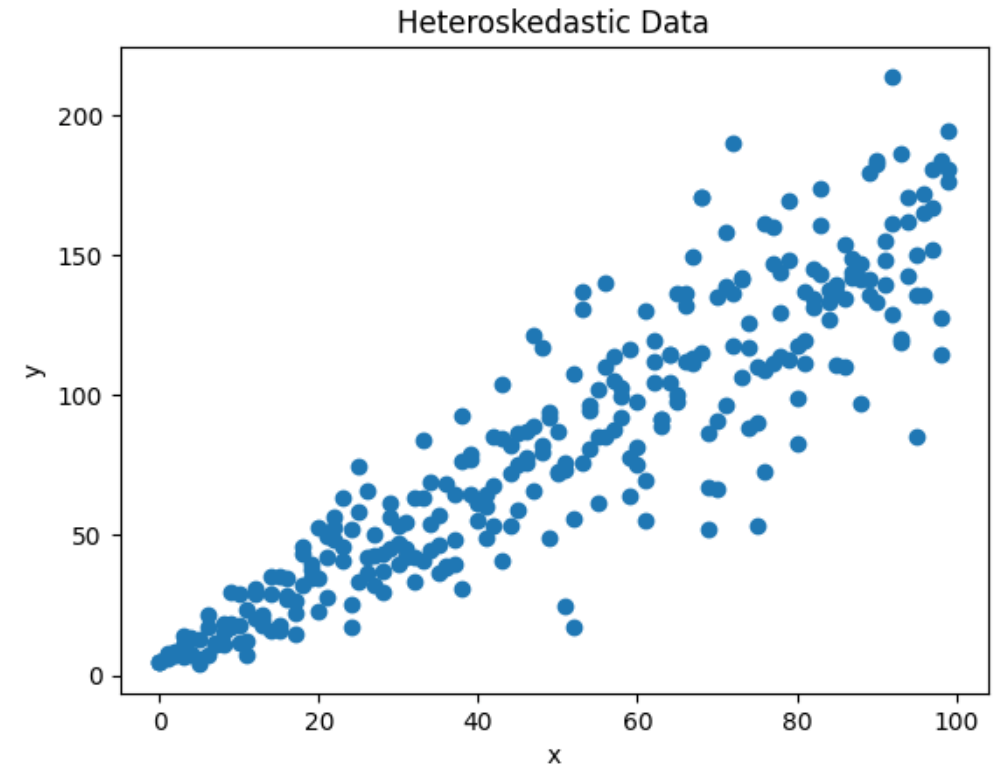


Weighted Least Squares (WLS) estimates

Recall: OLS, minimizing the sum of squared residuals:

$$S(\boldsymbol{\theta}) = \sum_{t=1}^n [y_t - f(\mathbf{x}_t; \boldsymbol{\theta})]^2 = \sum_{t=1}^n \varepsilon_t^2(\boldsymbol{\theta})$$

Where we assumed the residuals have the same variance and are mutually uncorrelated.



Weighted Least Squares (WLS) estimates

Recall: OLS, minimizing the sum of squared residuals:

$$S(\boldsymbol{\theta}) = \sum_{t=1}^n [y_t - f(\mathbf{x}_t; \boldsymbol{\theta})]^2 = \sum_{t=1}^n \varepsilon_t^2(\boldsymbol{\theta})$$

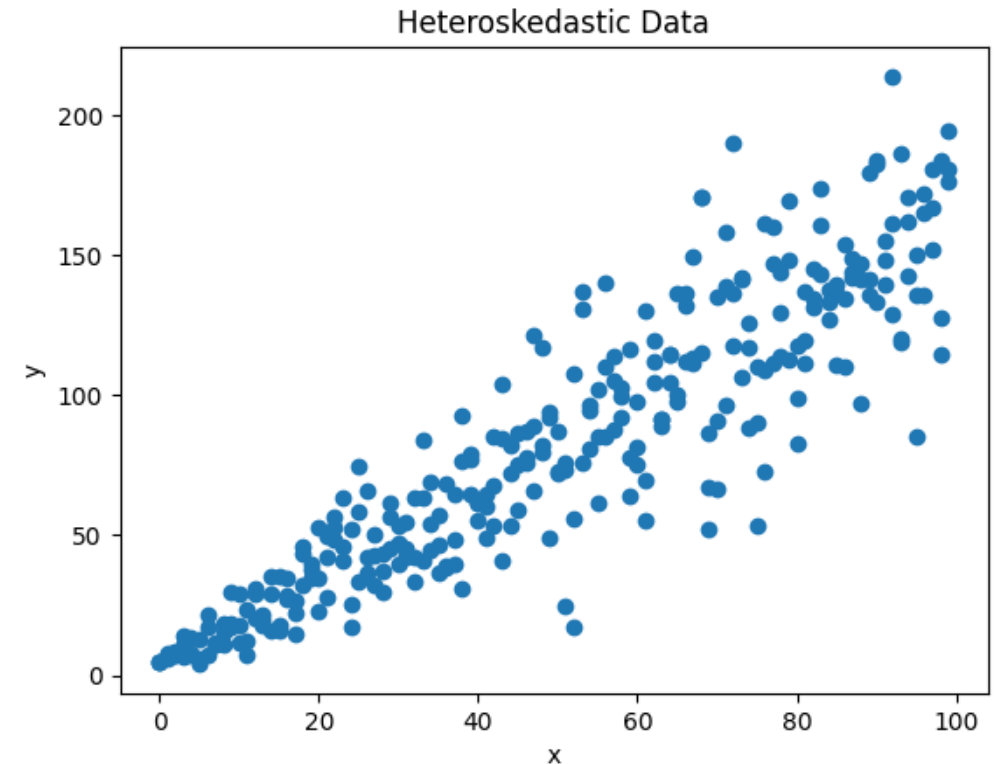
Where we assumed the residuals have the same variance and are mutually uncorrelated.

In WLS we assume the residuals can have different variances and be mutually correlated:

$$V[\boldsymbol{\varepsilon}] = E[\boldsymbol{\varepsilon}\boldsymbol{\varepsilon}^T] = \sigma^2 \boldsymbol{\Sigma}$$

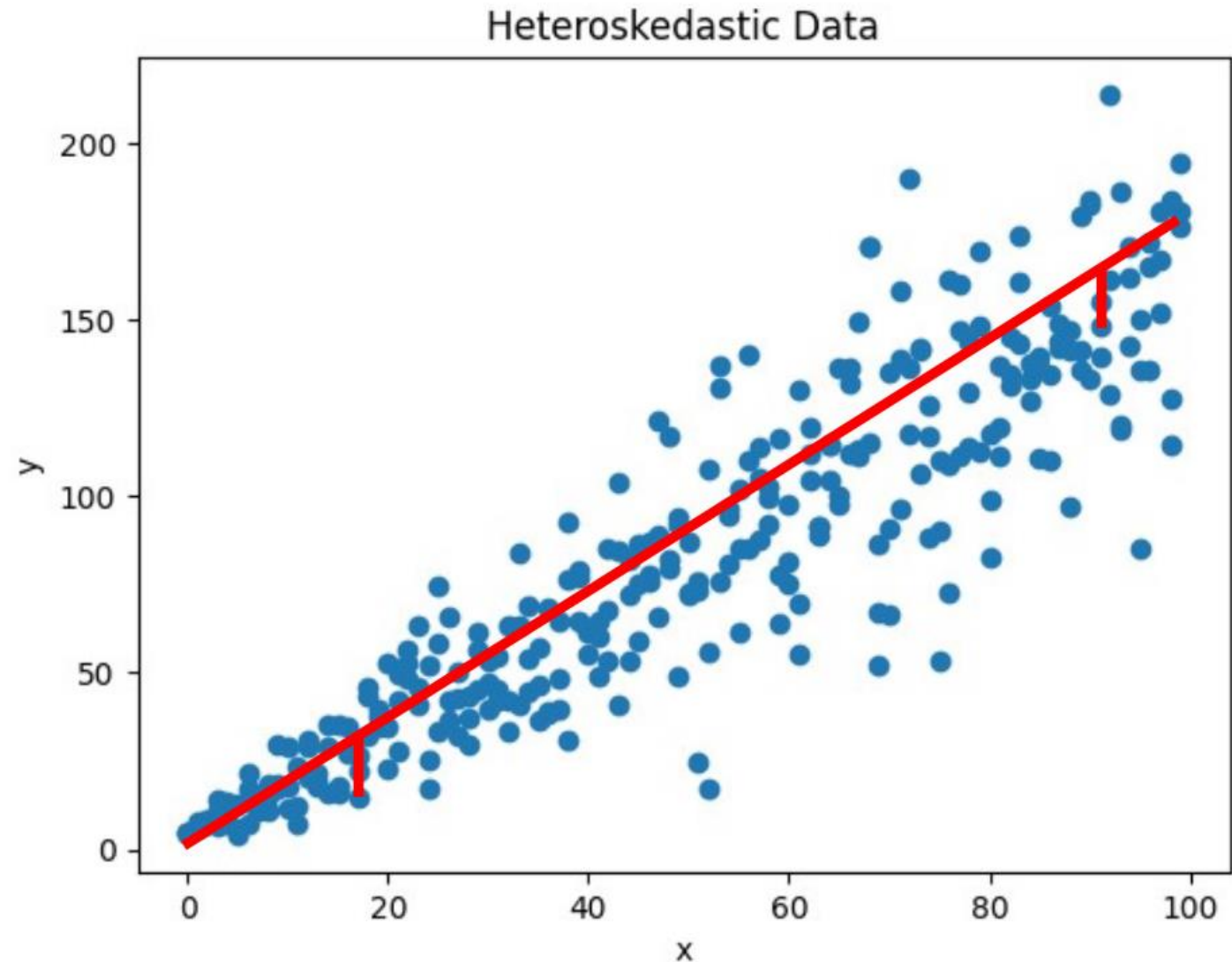
We minimize the *weighted* sum of squared residuals:

$$(\mathbf{Y} - \mathbf{x}\boldsymbol{\theta})^T \boldsymbol{\Sigma}^{-1} (\mathbf{Y} - \mathbf{x}\boldsymbol{\theta})$$



Weighted Least Squares (WLS) estimates

How would weighting residuals make sense for this data?



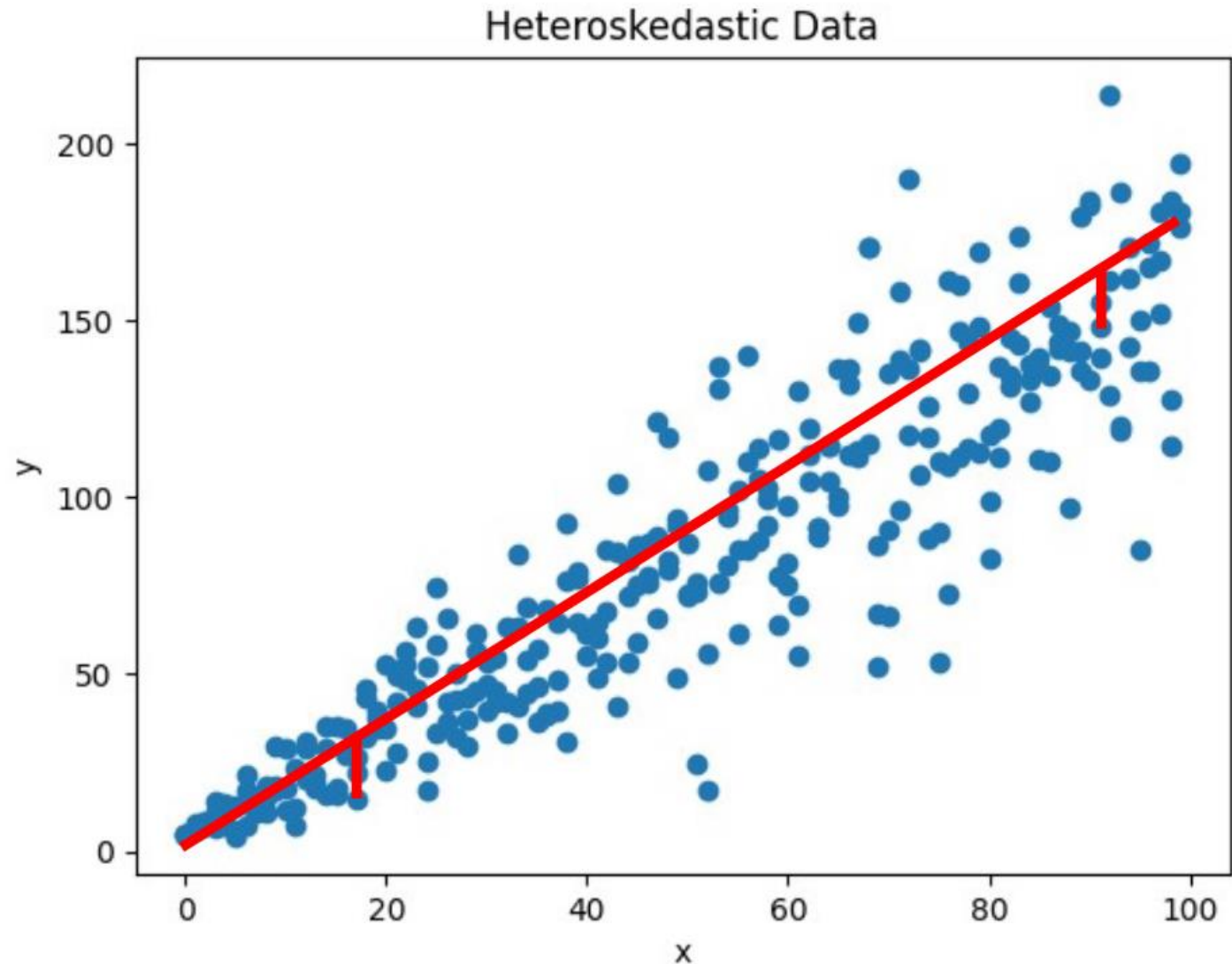
Weighted Least Squares (WLS) estimates

How would weighting residuals make sense for this data?

Large variance



Lower "weight"



WLS estimates for the general linear model

For all observations the model equations are written as:

$$\begin{bmatrix} Y_1 \\ \vdots \\ Y_n \end{bmatrix} = \begin{bmatrix} \mathbf{x}_1^T \\ \vdots \\ \mathbf{x}_n^T \end{bmatrix} \boldsymbol{\theta} + \begin{bmatrix} \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{bmatrix} \quad \text{or} \quad \mathbf{Y} = \mathbf{x}\boldsymbol{\theta} + \boldsymbol{\varepsilon}$$

We want to minimize $(\mathbf{Y} - \mathbf{x}\boldsymbol{\theta})^T \boldsymbol{\Sigma}^{-1} (\mathbf{Y} - \mathbf{x}\boldsymbol{\theta})$

The solution is

$$\hat{\boldsymbol{\theta}} = (\mathbf{x}^T \boldsymbol{\Sigma}^{-1} \mathbf{x})^{-1} \mathbf{x}^T \boldsymbol{\Sigma}^{-1} \mathbf{Y}$$

(if $\mathbf{x}^T \boldsymbol{\Sigma}^{-1} \mathbf{x}$ is invertible)

$$\hat{\sigma}^2 = \frac{1}{n-p} (\mathbf{Y} - \mathbf{x}\hat{\boldsymbol{\theta}})^T \boldsymbol{\Sigma}^{-1} (\mathbf{Y} - \mathbf{x}\hat{\boldsymbol{\theta}}) \quad V[\hat{\boldsymbol{\theta}}] = E[(\hat{\boldsymbol{\theta}} - \boldsymbol{\theta})(\hat{\boldsymbol{\theta}} - \boldsymbol{\theta})^T] = (\mathbf{x}^T \boldsymbol{\Sigma}^{-1} \mathbf{x})^{-1} \sigma^2$$

Maximum likelihood estimates

- ▶ Assume that the observations are Gaussian;

$$Y \sim N_n(\mathbf{x}\boldsymbol{\theta}, \sigma^2\boldsymbol{\Sigma})$$

- ▶ and that $\boldsymbol{\Sigma}$ is known.
- ▶ The ML-estimator is (here) the same as the WLS-estimator:

$$\hat{\boldsymbol{\theta}} = (\mathbf{x}^T \boldsymbol{\Sigma}^{-1} \mathbf{x})^{-1} \mathbf{x}^T \boldsymbol{\Sigma}^{-1} \mathbf{Y}$$

- ▶ The ML-estimator for σ^2 is

$$\hat{\sigma}^2 = \frac{1}{n} (\mathbf{Y} - \mathbf{x}\hat{\boldsymbol{\theta}})^T \boldsymbol{\Sigma}^{-1} (\mathbf{Y} - \mathbf{x}\hat{\boldsymbol{\theta}})$$

- ▶ OLS and WLS estimates can be interpreted as? assumptions of Gaussianity.

WLS variance-covariance examples

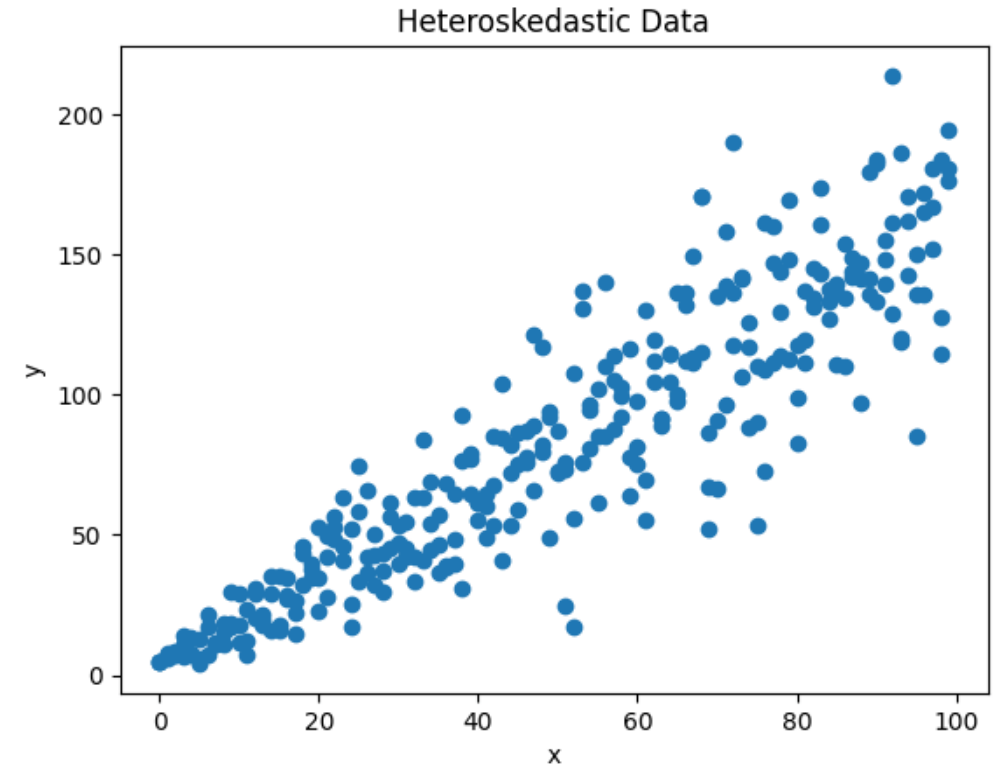
$$V[\boldsymbol{\varepsilon}] = E[\boldsymbol{\varepsilon}\boldsymbol{\varepsilon}^T] = \sigma^2\boldsymbol{\Sigma}$$

$$\boldsymbol{\Sigma} = \begin{bmatrix} \sigma_{11} & \sigma_{12} & \sigma_{13} & \dots & \sigma_{1n} \\ \sigma_{21} & \sigma_{22} & \sigma_{23} & \dots & \sigma_{2n} \\ \sigma_{31} & \sigma_{32} & \sigma_{33} & \dots & \sigma_{3n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \sigma_{n1} & \sigma_{n2} & \sigma_{n3} & \dots & \sigma_{nn} \end{bmatrix}$$

WLS variance-covariance examples

$$V[\boldsymbol{\varepsilon}] = E[\boldsymbol{\varepsilon}\boldsymbol{\varepsilon}^T] = \sigma^2\boldsymbol{\Sigma}$$

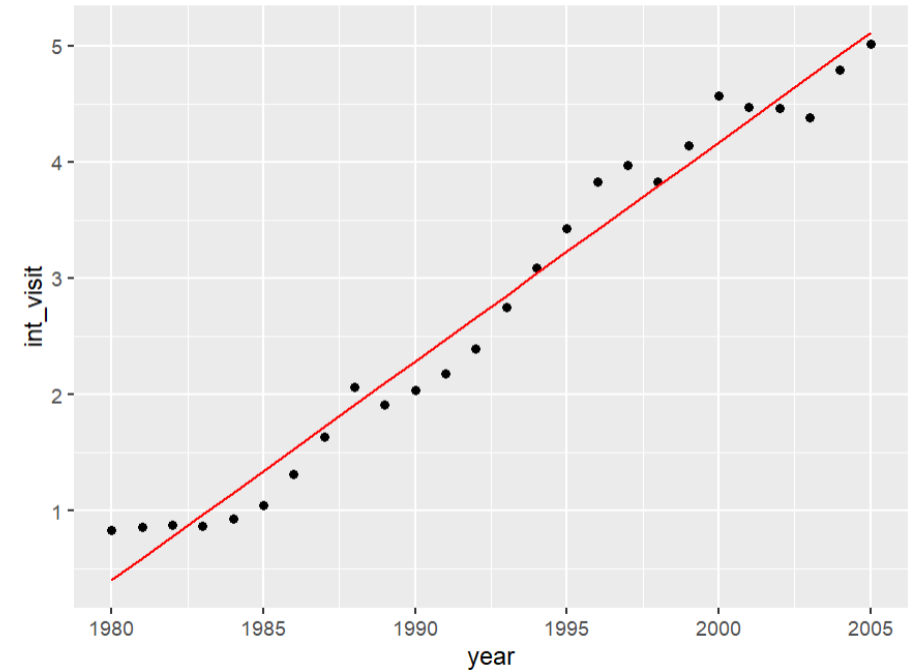
$$\boldsymbol{\Sigma} = \begin{bmatrix} \sigma_{11} & 0 & 0 & \dots & 0 \\ 0 & \sigma_{22} & 0 & \dots & 0 \\ 0 & 0 & \sigma_{33} & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & \sigma_{nn} \end{bmatrix}$$



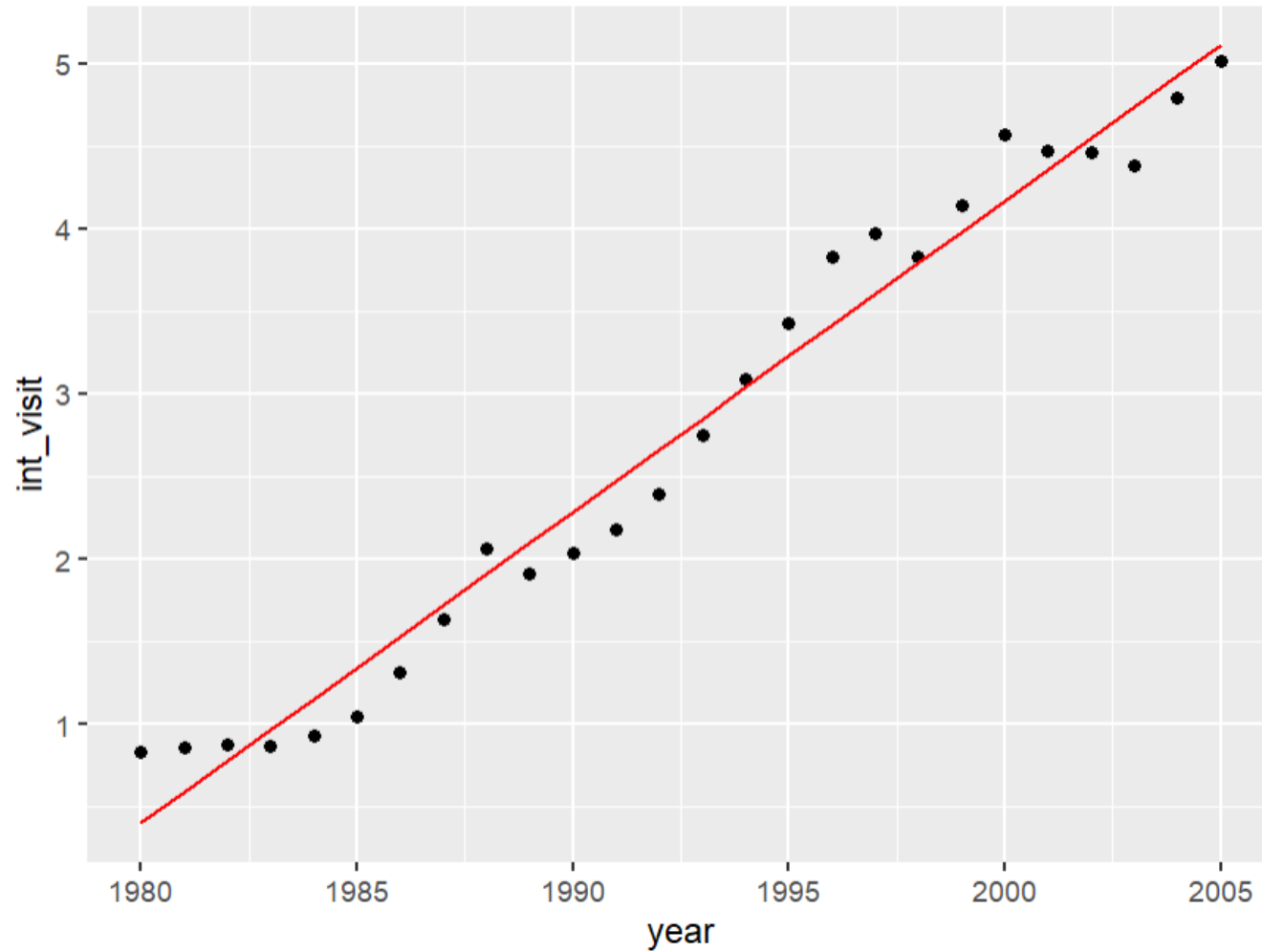
WLS variance-covariance examples

$$V[\boldsymbol{\varepsilon}] = E[\boldsymbol{\varepsilon}\boldsymbol{\varepsilon}^T] = \sigma^2 \boldsymbol{\Sigma}$$

$$\boldsymbol{\Sigma} = \begin{bmatrix} 1 & \rho^1 & \rho^2 & \dots & \rho^n \\ \rho^1 & 1 & \rho^1 & \dots & \rho^{n-1} \\ \rho^2 & \rho^1 & 1 & \dots & \rho^{n-2} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \rho^n & \rho^{n-1} & \rho^{n-2} & \dots & 1 \end{bmatrix}$$



Example in R

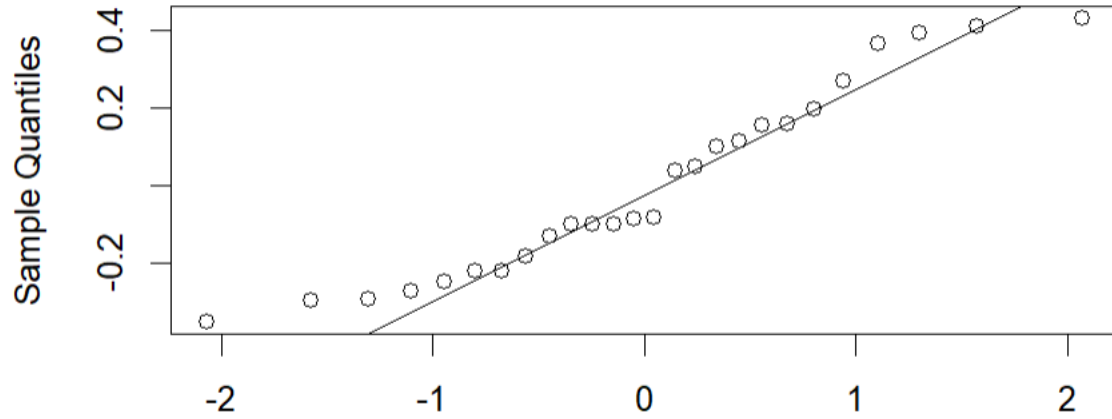


Is it a good model?

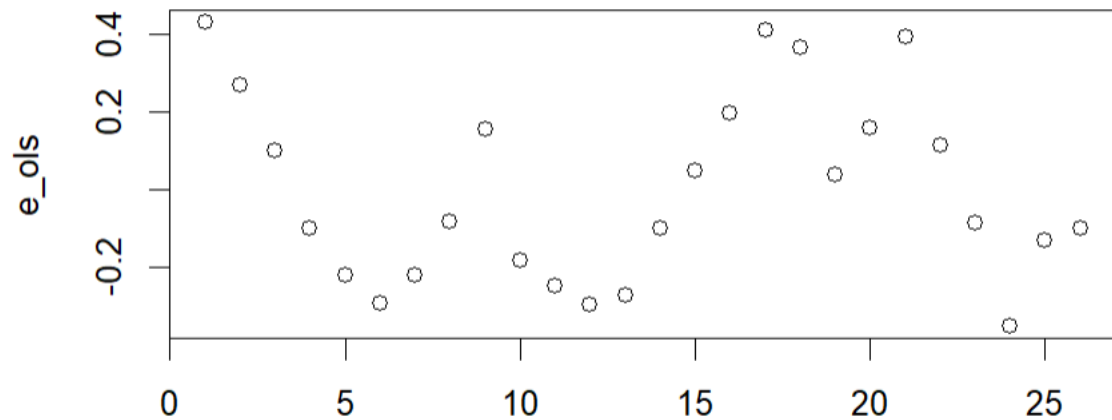
We should inspect the residuals!

Example in R

Normal Q-Q Plot



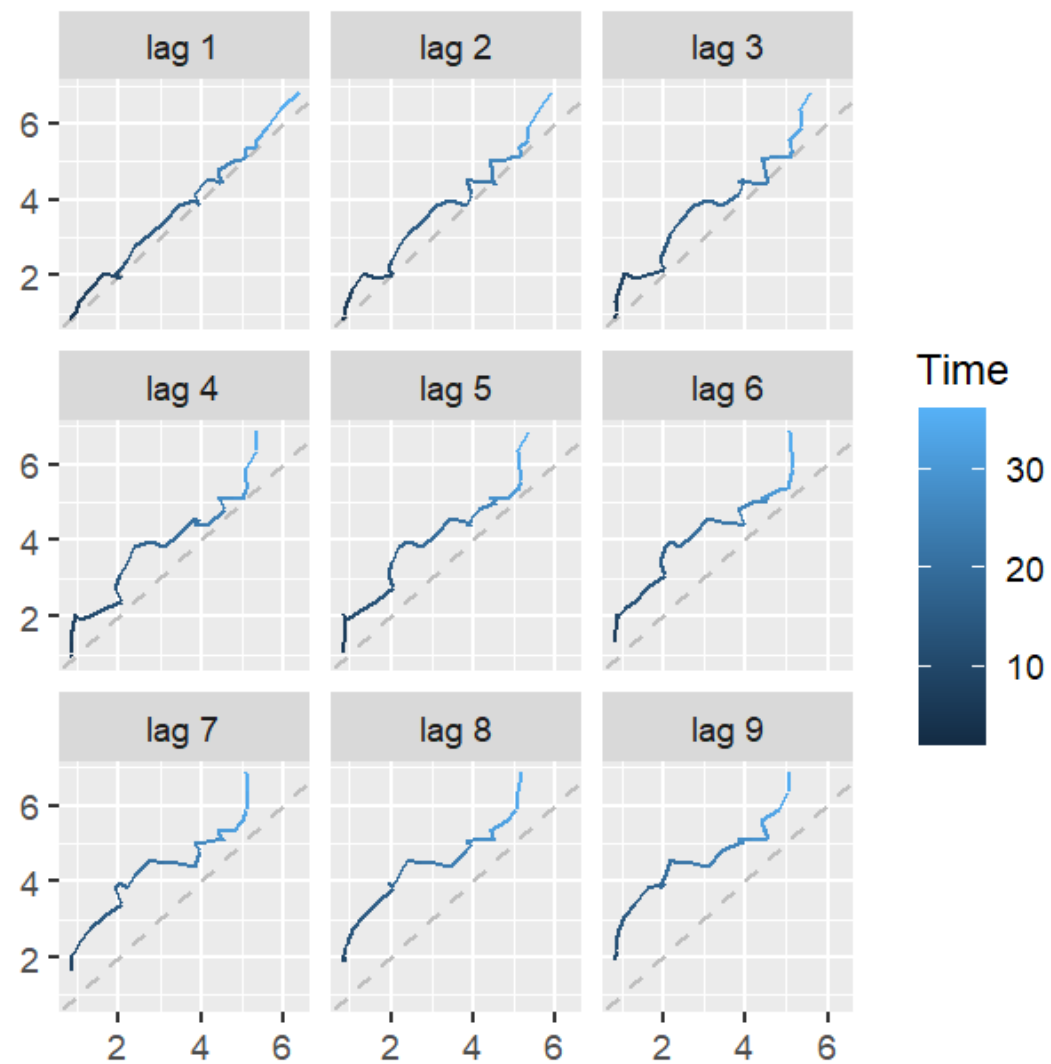
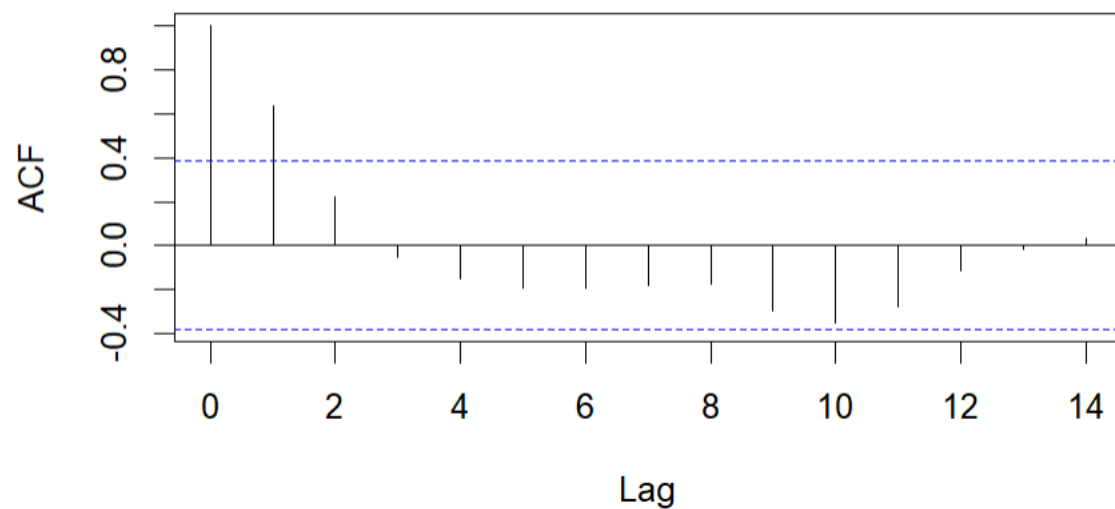
Are the residuals normally distributed?



Is there a pattern in the residuals?

Example in R

We can also inspect the autocorrelations of the residuals



Example in R

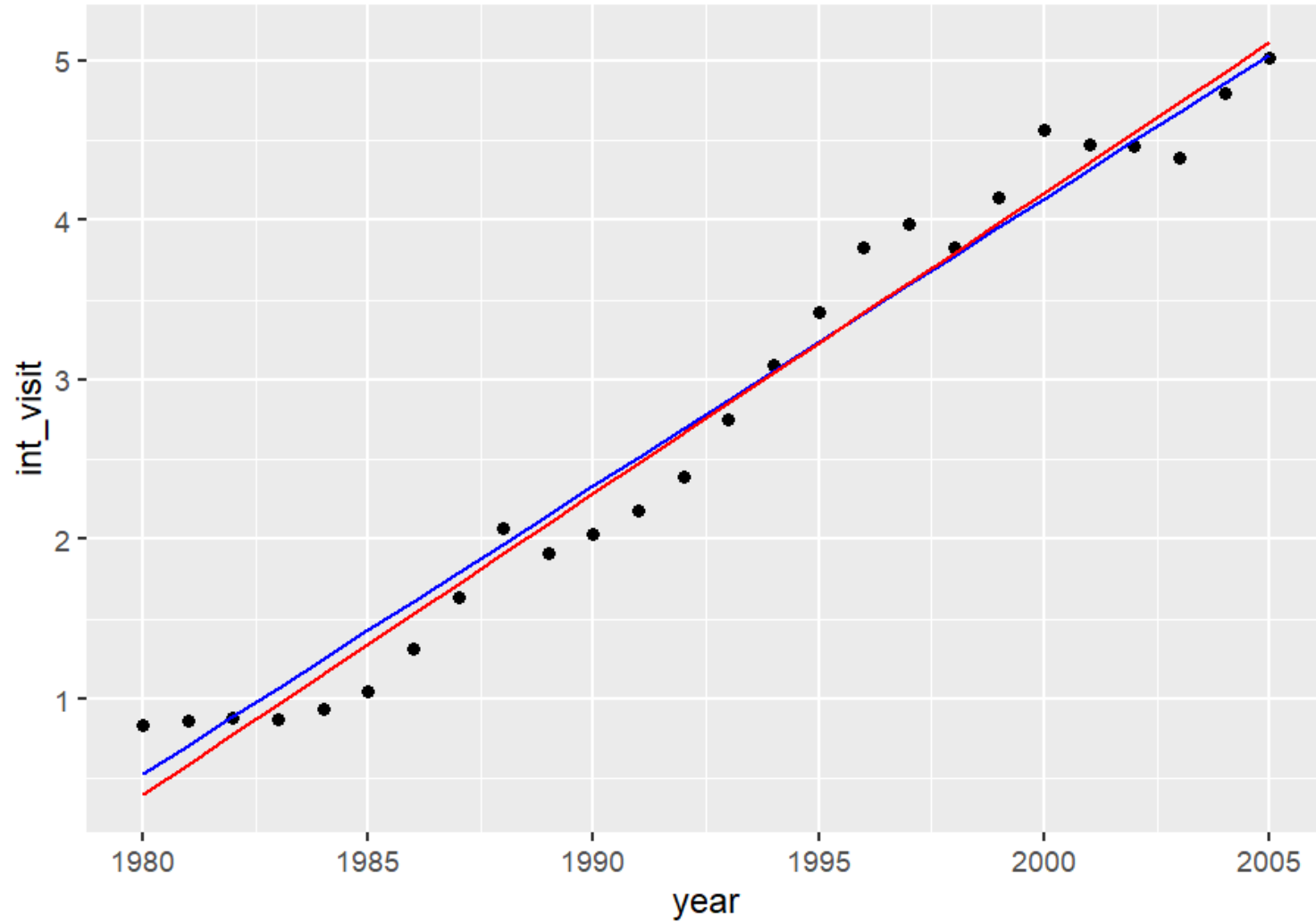
```
> print(SIGMA[1:5,1:5])
      [,1] [,2] [,3] [,4] [,5]
[1,] 1.0000 0.700 0.49 0.343 0.2401
[2,] 0.7000 1.000 0.70 0.490 0.3430
[3,] 0.4900 0.700 1.00 0.700 0.4900
[4,] 0.3430 0.490 0.70 1.000 0.7000
[5,] 0.2401 0.343 0.49 0.700 1.0000
```

```
WLS <- solve(t(X)%*%solve(SIGMA)%*%X)%*%(t(X)%*%solve(SIGMA)%*%y)
```

```
print(WLS)
# [1,] -356.7172120
# [2,]  0.1804264
```

The estimated parameters are slightly different

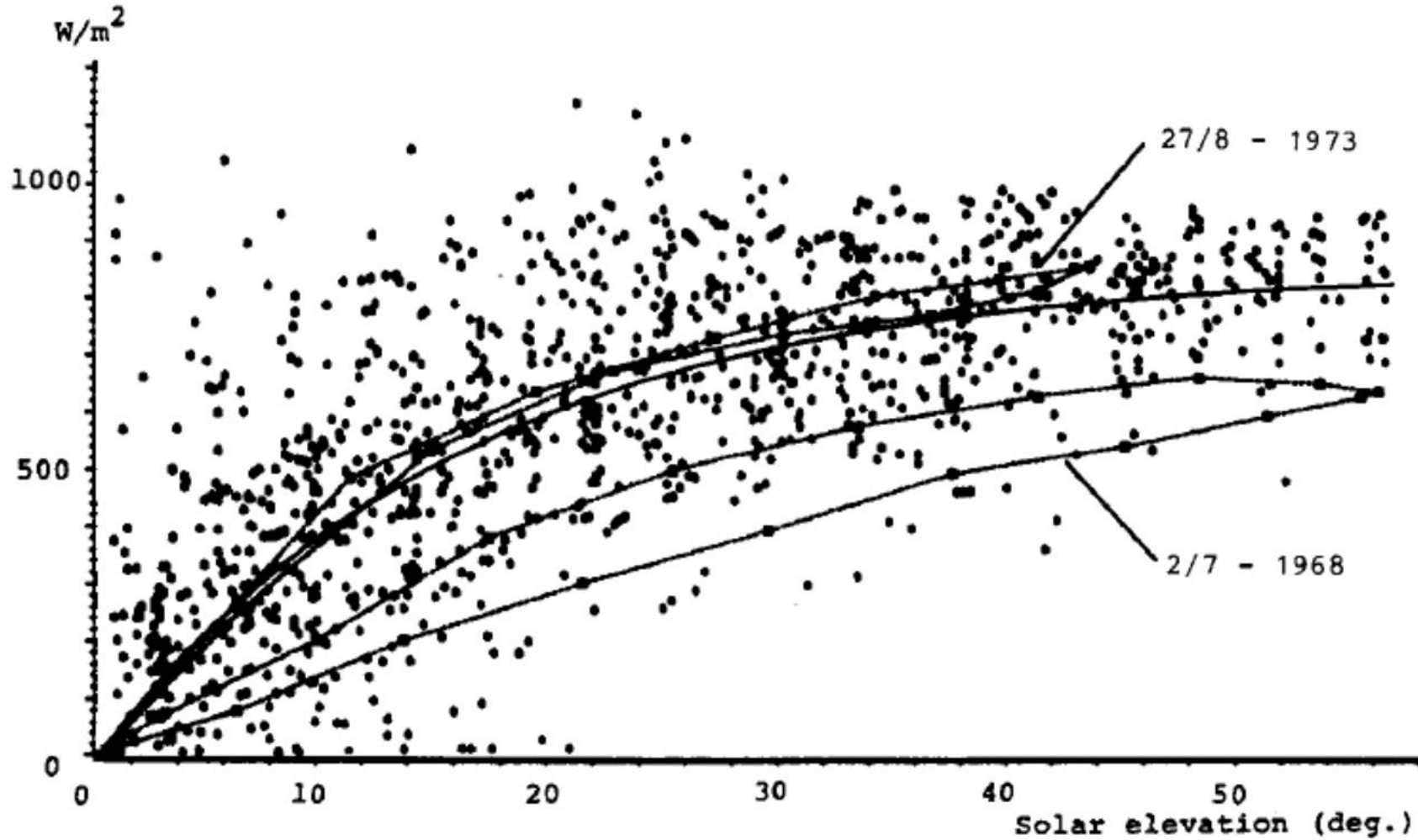
Example in R



Blue is WLS

Red is OLS from before

Example from the book



Variance is larger for small angles

AND

Observations are correlated in time

$$\Sigma_{ij} = \frac{\rho^{|t_i - t_j|}}{\sin(h_{t_i}) \sin(h_{t_j})}$$

Next time

- Combine weights (WLS) with trend models to make "local trend models"
- "Exponential smoothing"